

The Future of Transportation: Achieving Equity and Mobility through Self-Driving Vehicles

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Overview

- Levels of vehicle automation
- Concept vehicle and transportation system
- Motivating factors for improved transportation
- Potential benefits of self-driving vehicles
- Trends: Transportation in the year 2045
- Opportunities
- Challenges
- VTTI's Automated Vehicle Research

Are we there yet? Are we there yet? Are there yet?



	SAE Level	Name	Steering, acceleration, deceleration	Monitoring driving environment	Fallback performance of dynamic driving task	System capability (driving modes)
Human monitors environment	0	No automation the full-time performance by the human driver of all aspects of the dynamic driving task, even when enhanced by warning or intervention systems				
	1	Driver assistance the driving mode-specific execution by a driver assistance system of either steering or acceleration/deceleration using information about the driving environment and with the expectation that the human driver perform all remaining aspects of the dynamic driving task.				Some driving modes
	2	Partial automation the driving mode-specific execution by one or more driver assistance systems of both steering and acceleration/deceleration using information about the driving environment and with the expectation that the human driver perform all remaining aspects of the dynamic driving task				Some driving modes
Car monitors environment	3	Conditional automation the driving mode-specific performance by an automated driving system of all aspects of the dynamic driving task with the expectation that the human driver will respond appropriately to a request to intervene				Some driving modes
	4	High automation the driving mode-specific performance by an automated driving system of all aspects of the dynamic driving task, even if a human driver does not respond appropriately to a request to intervene				Some driving modes
	5	Full automation the full-time performance by an automated driving system of all aspects of the dynamic driving task under all roadway and environmental conditions that can be managed by a human driver				All driving modes

SAE J3016: Taxonomy and Definitions for Terms Related to On-Road Motor Vehicle Automated Driving Systems

Nissan IDS Concept Technology



- Connectivity
- Mapping
- Machine vision
- 360 recognition
 - Radar, Lidar, other
- Dynamic scheduling
- Pedestrian/cyclist
- Wireless charging lanes/parking
- Transfer of control
- Piloted parking

What's the Future of Transportation?



We need new or extended connections to employment, education, healthcare, and other essential services

Second only to housing, currently transportation costs are the largest expense for American households – costing more than food, clothing, and healthcare
(Bureau of Labor Statistics, 2015)



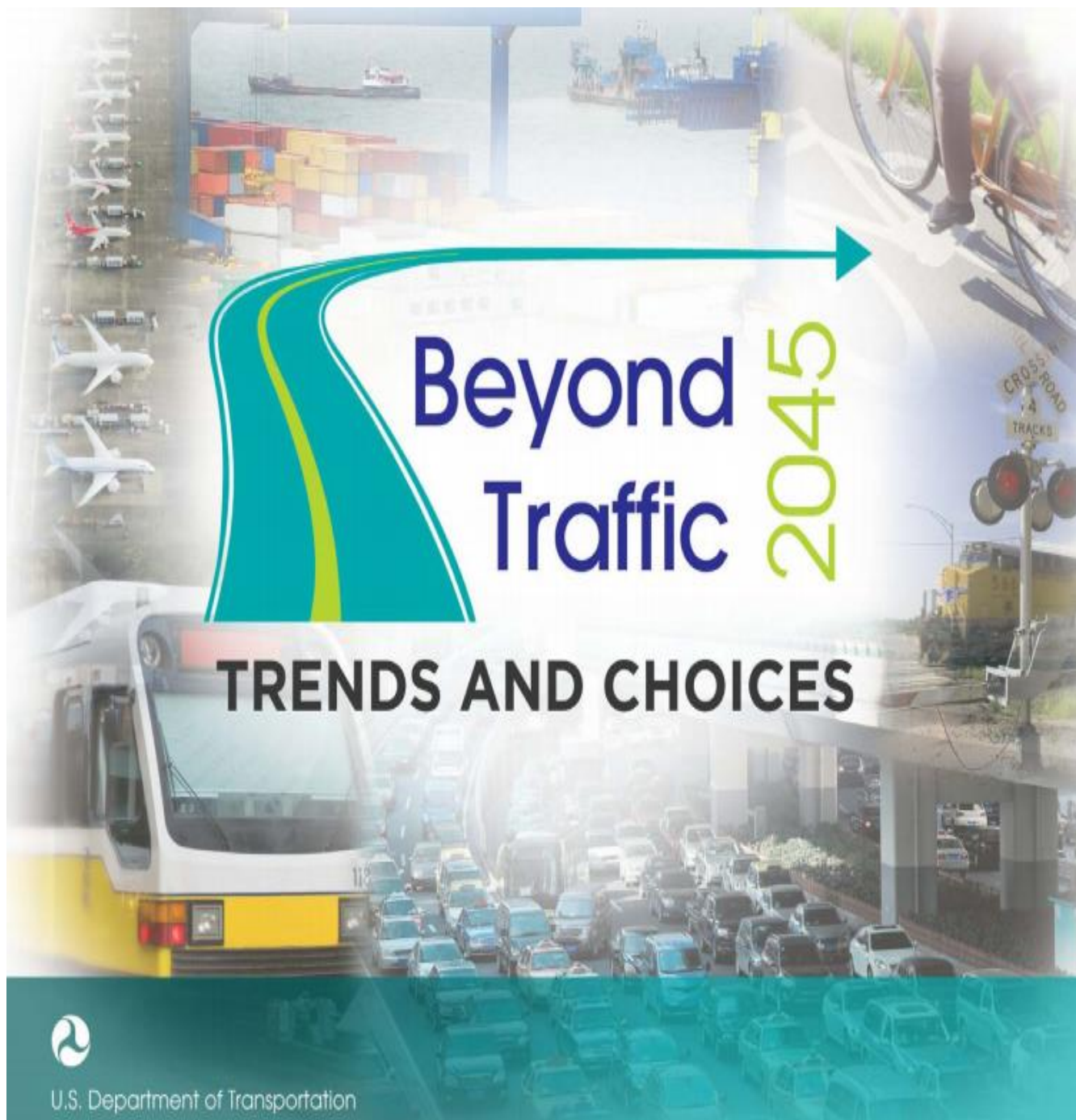
Motivating Factors for Improved Transportation

- Communities designed with the car in mind
- Urban sprawl
 - Difficult to get anywhere without a car
 - Highest transportation expenditures
- American Public Transportation Association
 - Small towns and rural communities
 - 2/3 of all residents have limited transportation options
 - 41% of residents have no access to transit
 - 25% have below-average transit services
- Who's living without a car? (Berube, Deakin, & Raphael, 2006)
 - 20% of African-American households
 - 14% of Latino households
 - 13% of Asian households

Potential Benefits of Self-Driving Vehicles



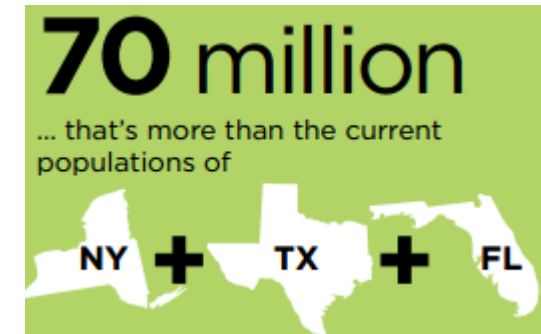
- Health
- Employment
- Age in place
- Quality of life
- Safety
 - ~32,000 vehicle related fatalities
 - ~5,000 pedestrians and bicyclist



How will the future look if we don't invest in a new transportation system?

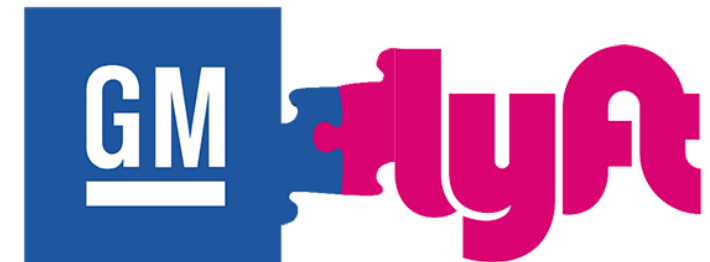
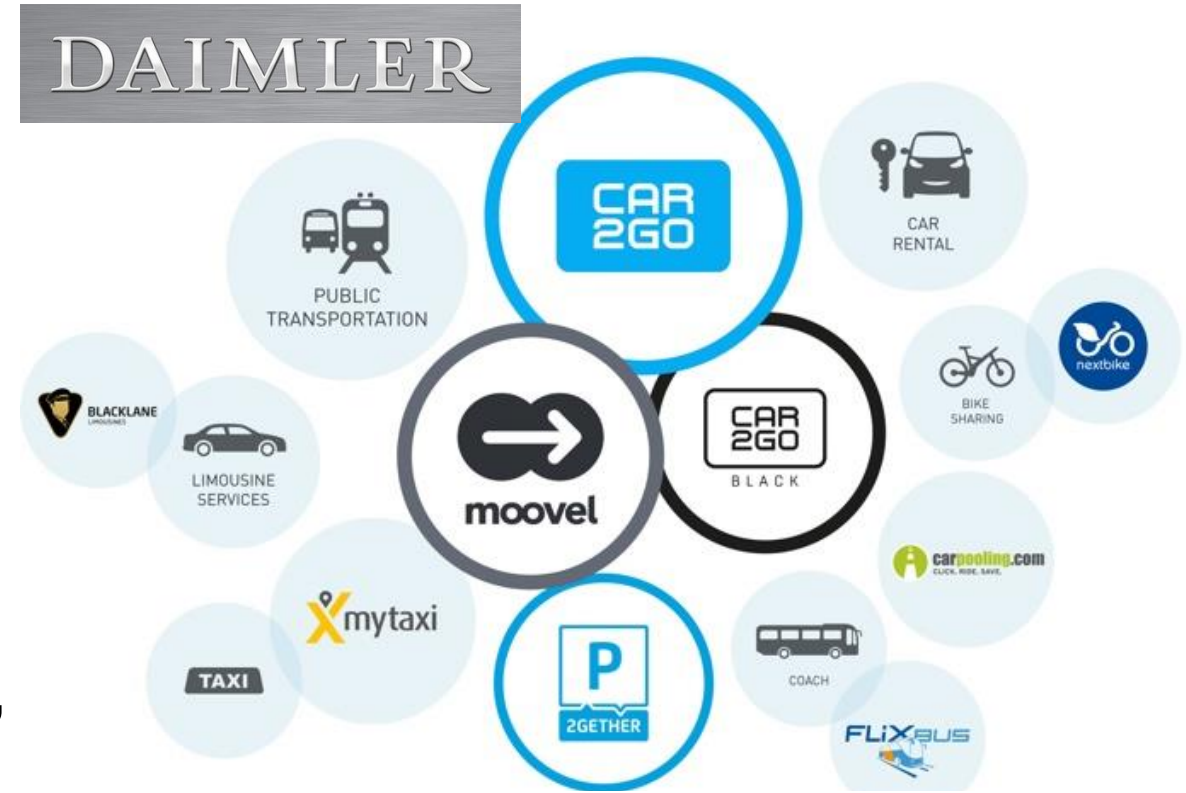
Trends: 2045

- Population will grow by **70 million** and will have **twice** the number of **seniors**
- People will start moving towards **megaregions**
- **Freight** will increase by **45%** due to online shopping
- People will **reduce trips** by **private car** in favor of other modes of transportation
- Consolidation of airline hubs and many mergers will make us **rethink traditional travel**
- **Robotic** systems will assist with infrastructure maintenance
- **Climate change** will alter sea level, increase temperatures, and develop more frequent and adverse climate events (e.g., hurricanes)



Opportunities for Current and Emerging Self-Driving Vehicle Applications

- Mobility On-Demand
 - **Group rapid transit:** public transportation, vanpools, and ridesharing
 - **Personal rapid transit:** personal vehicles, last-mile services (including parking valet alternatives), taxi and on-demand services



Potential Challenges Associated with Implementation

- Legacy vehicles
- Fail-safe & fail-operational states
- Safe harbor
- External communications
- Security
- Accessibility
- Multi-jurisdictional collaboration
- Policies

Automated Vehicle Research

- Sample studies
 - Human Factors Evaluation of Level 2 and Level 3 Automated Driving Concepts
 - Automated Vehicle Crash Rate Comparison Using Naturalistic Data



Human Factors Evaluation of Level 2 and Level 3 Automated Driving Concepts

Experiment 1
(L2 ADS)



2009 Chevy Malibu



Experiment 2
(L2 ADS)



2010 Cadillac SRX



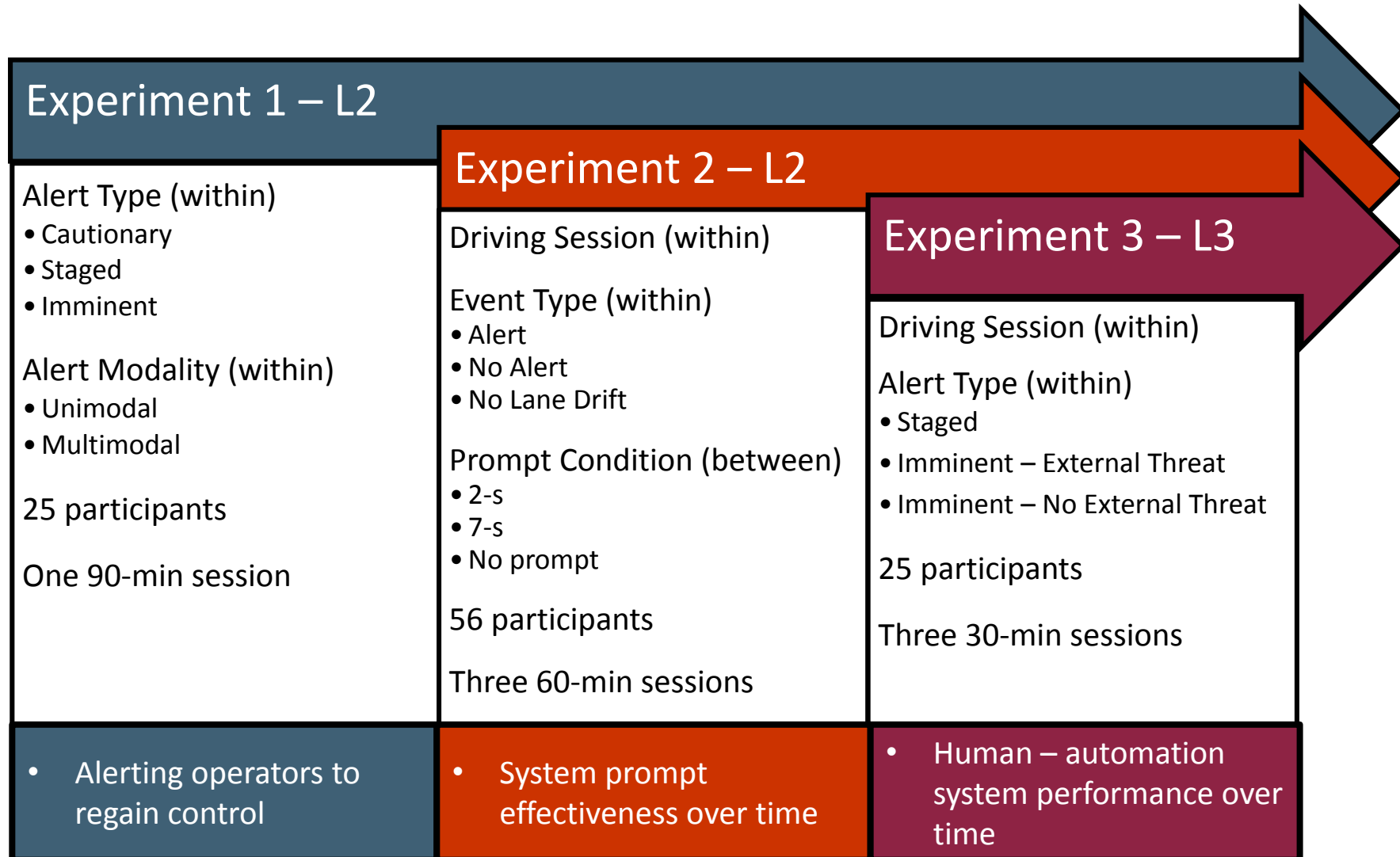
Experiment 3
(L3 ADS)



2012 Lexus RX450h



Experimental Design



Key Takeaways

- Take Over Request

- Most effective hand-off strategies were those that incorporated nonvisual components
 - Effective countermeasures to primary task reversals when drivers performed non-driving tasks

- Regain Control

- L2 mean of 1.3 s (S.E. = 0.1 s)
 - Imminent visual and haptic alert
- L3 mean of 2.3 s (S.E. = 0.2 s)
 - Imminent visual plus auditory alert

- Trust

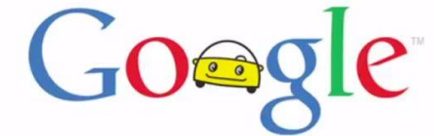
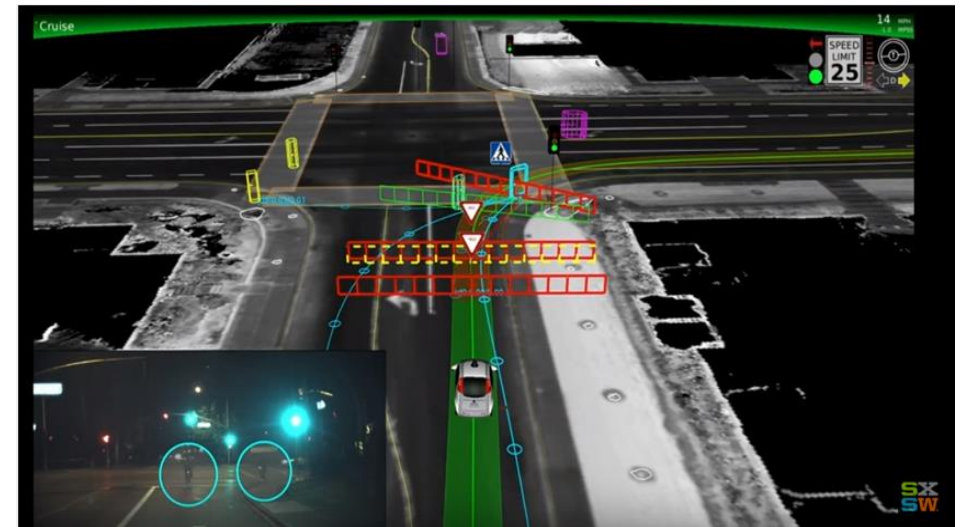
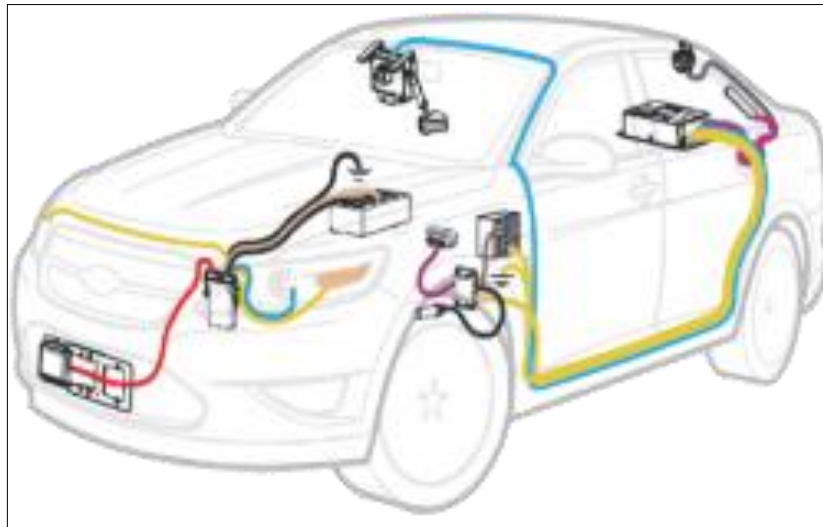
- High trust in automation for both levels of automation but calibrated
 - Trust was reduced after events where something occurred unannounced

Vehicle Automation Theories

- Primary Task Reversal
- Alert Annoyance Habituation



Automated Vehicle Crash Rate Comparison Using Naturalistic Data



Self-Driving Car Project

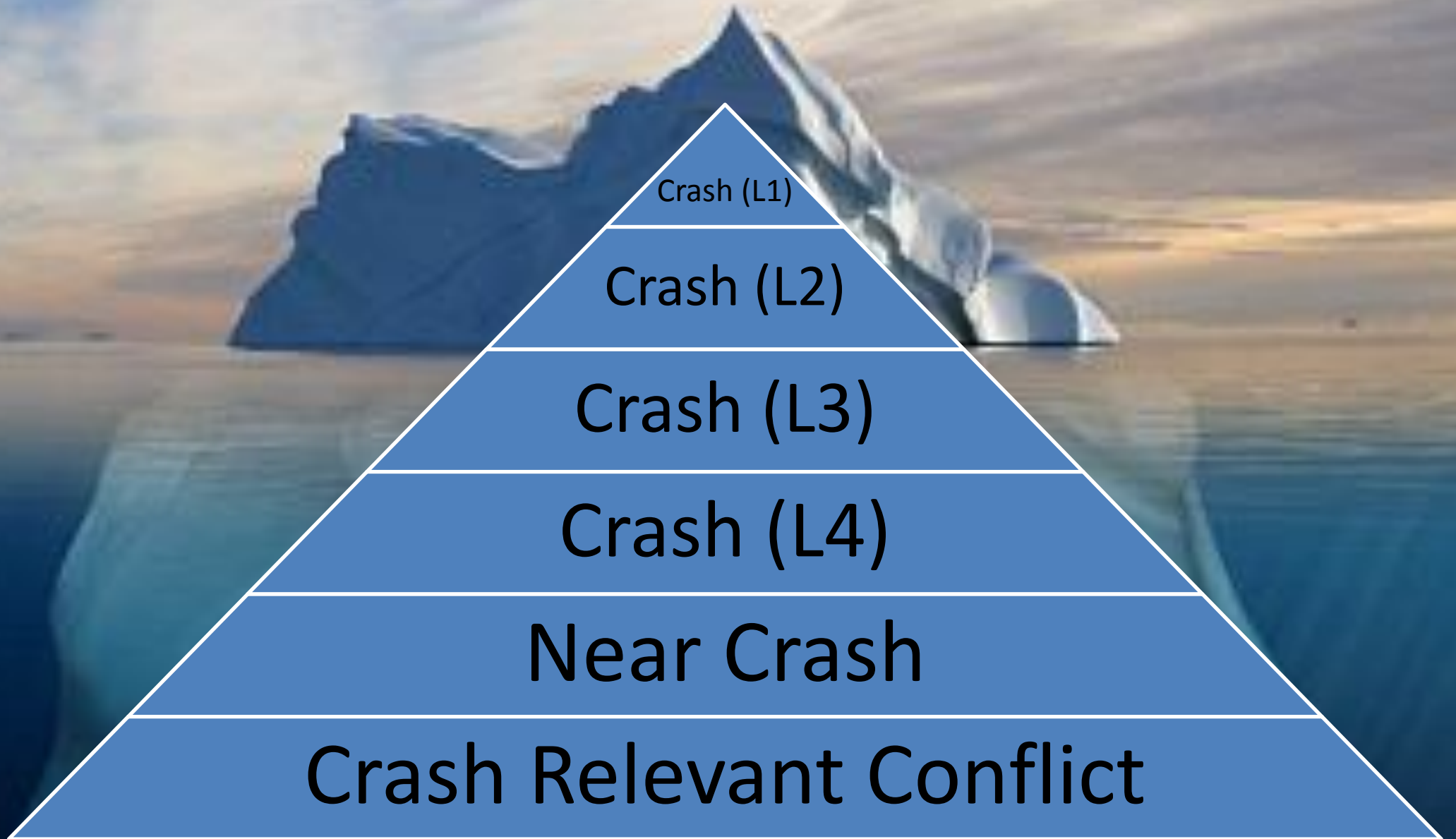
SHRP 2 Naturalistic Data Study

- 34 million VMT
- 2 petabytes of data
- 3,542 drivers
- > 3,300 vehicles
- > 1,600 crashes
- 4,368 data years
- 5,512,900 trip files



**What can 1,000,000 hours of watching
and measuring drivers can tell you?**

Heinrich Triangle



Self-Driving Car Project Data

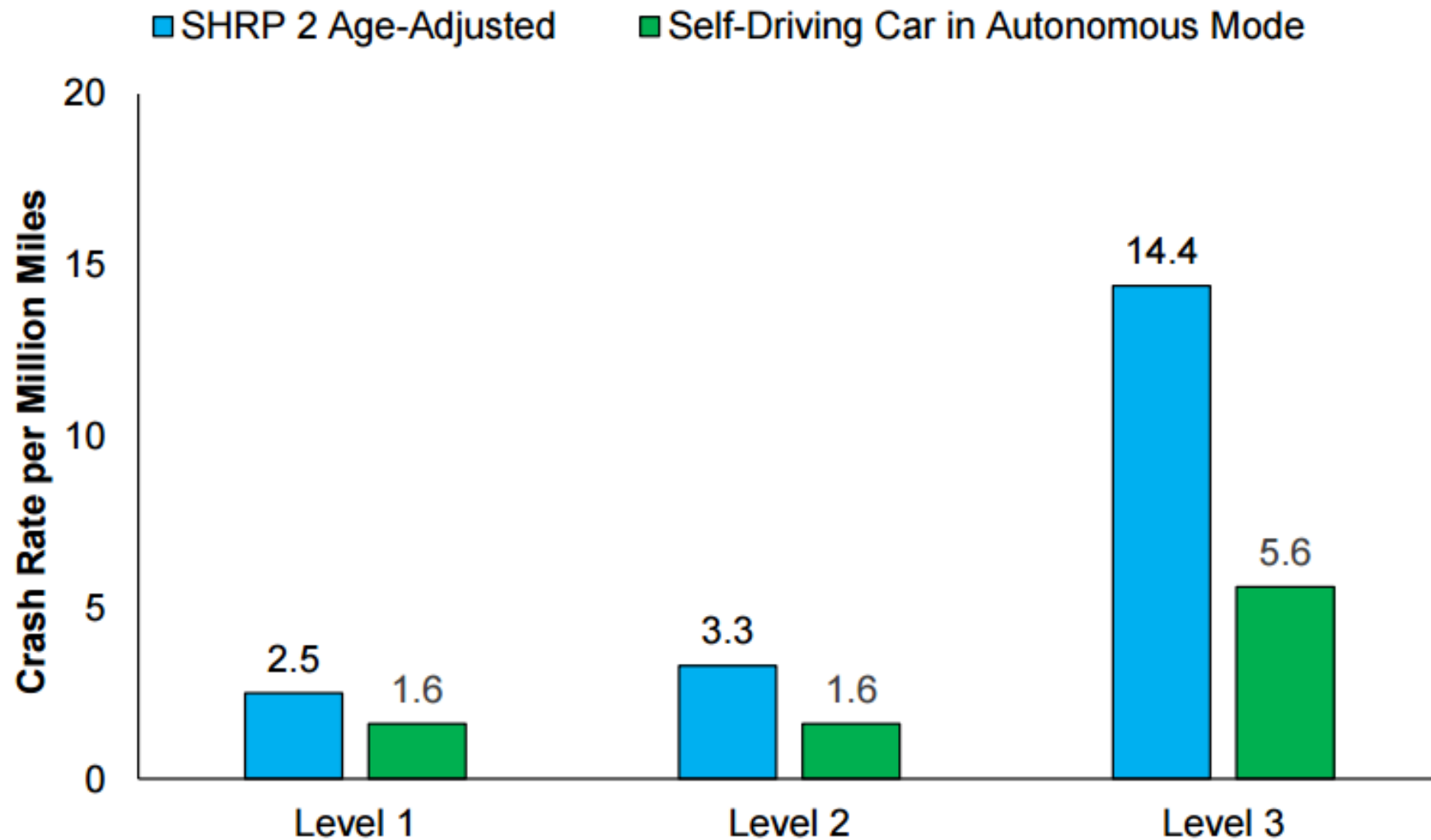
- Data received for period 2009 - October 31, 2015
 - Mountain View, CA
 - 1,266,611 miles
 - 2010: First crash
 - 2012: First crash in autonomous mode
- 16 Crashes
 - 5 driver in control
 - 11 autonomous
 - None at-fault



SHRP 2 and Self-Driving Car Crash Summary

Crash Severity Level	SHRP 2 - Overall	SHRP 2 - with Police Report	Self-Driving Car
Level 1	120	34	2
Level 2	179	12	2
Level 3	633	0	7

Crash Comparison



What else is VTTI doing?

- Policy impact
- Develop advanced testing facilities
- Perform pragmatic research



HB 454 Motor vehicles; vehicles not to be equipped with televisions and video within view of driver.

Introduced by: Glenn R. Davis | all patrons ... notes | add to my profiles

SUMMARY AS PASSED: (all summaries)

Motor vehicles equipped with television and video. Provides that motor vehicles may be equipped with visual displays of moving images if the equipment is factory-installed and has an interlock device that disables the equipment when the motor vehicle operator is performing a "driving task," which is defined by the bill. Current law allows equipment with a visual display of a television broadcast or signal if the equipment's interlock disables when the motor vehicle is driven. The bill would allow the viewing of a visual display while the vehicle is being operated autonomously. The bill also provides that vehicles used by universities for vehicle technology research are not required to have government plates. This bill is identical to **SB 286**.

Smart Road Test Track & All-Weather Testing



NextGen DAS



MiniDAS

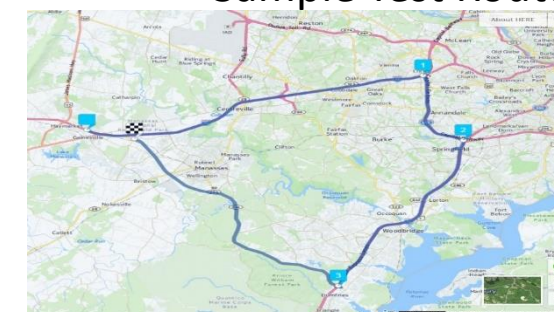
Virginia International Raceway



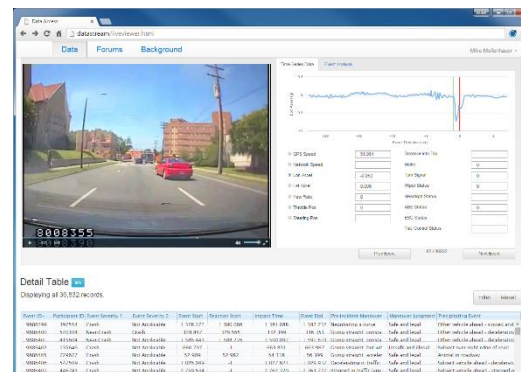
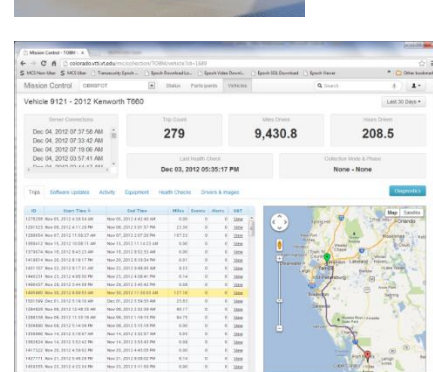
Virginia Connected Corridor



Virginia Automated Corridor Sample Test Route



Virginia Automated Corridors



Questions?



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