

WELCOME TO THE NAE US FRONTIERS OF ENGINEERING SYMPOSIUM 2005



Ongoing Challenges in Face Recognition

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How are people identified?

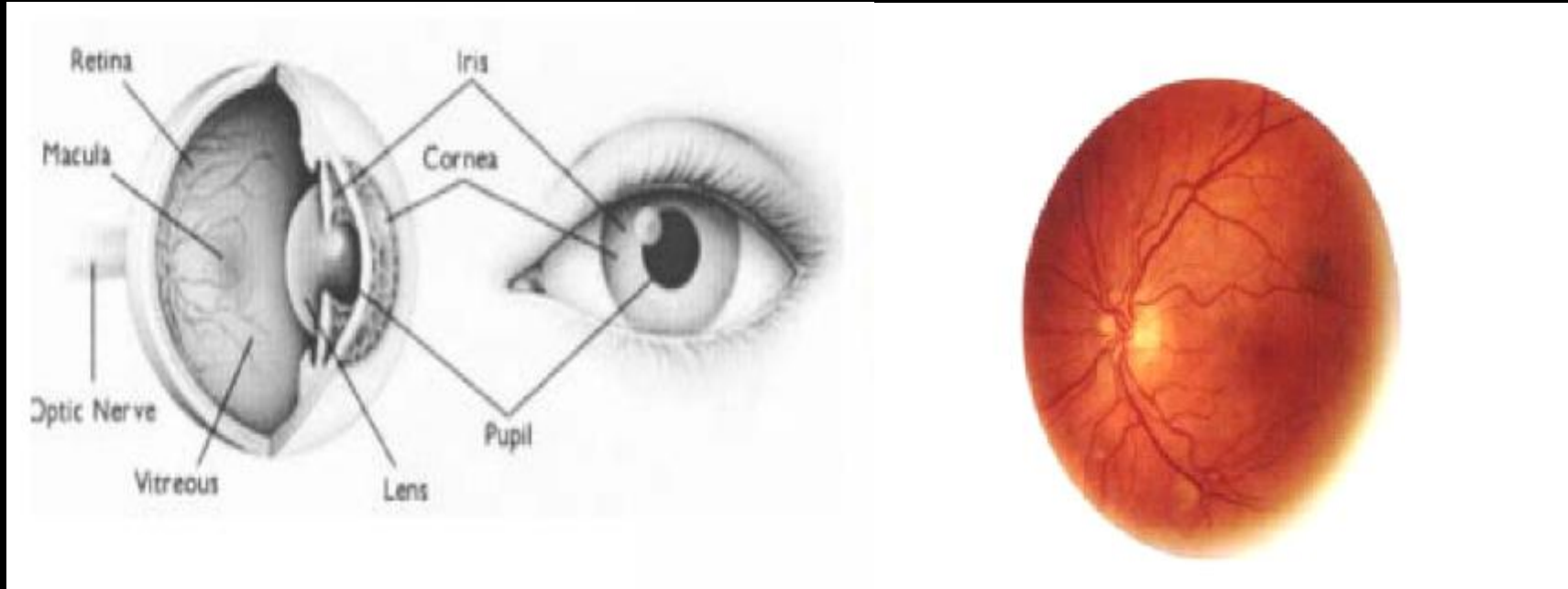
People are identified by three basic means:

- Something they **have** (identity document or token)
- Something they **know** (password, PIN)
- Something they **are** (human body)

Iris

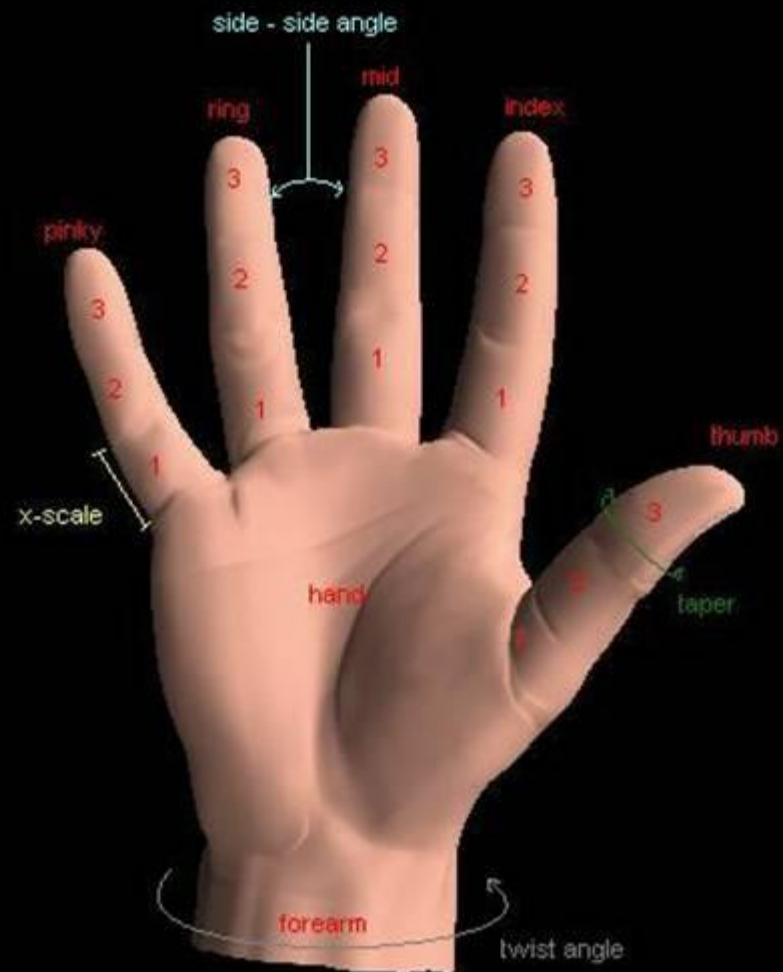


Retina



Every eye has its own totally unique pattern of blood vessels.

Hand



Fingerprint

INVESTIGATIONS-OEM

LEAVE THIS SPACE BLANK

INVESTIGATIONS-OEM

NAME Nixon/ Richard M.
(Typewritten) (Last name) (First name) (Initial or initials)

Position to which appointed Associate Attorney

Department and Bureau OEM Office of Price Admin.

Location Washington, D. C.

Class. 13.59 ROOM 1

Ref. 25 64 WOOD

RIGHT HAND

1. Thumb	2. Index Finger	3. Middle Finger	4. Ring Finger	5. Little Finger

LEFT HAND

6. Thumb	7. Index Finger	8. Middle Finger	9. Ring Finger	10. Little Finger

Classified _____ Assembled _____

Searched _____ Verified _____

Index Card _____ Answered _____

Note Amputations _____

Four Fingers Taken Simultaneously

Left Hand	L. Thumb	R. Thumb	Right Hand

Form 2270—January 1941. Applicant must fill blanks on back regarding places of residence and must give other information requested 10-6423

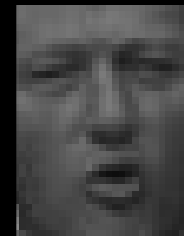
Ear



Face



Who are these people?



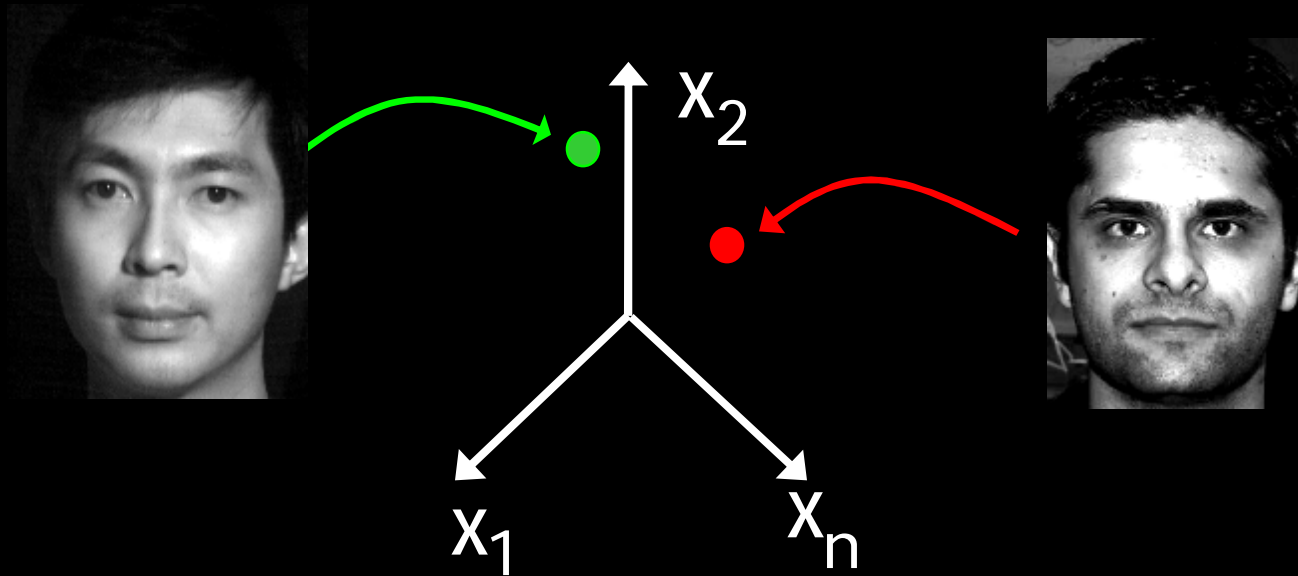
[Sinha and Poggio 1996]

Who are these people?



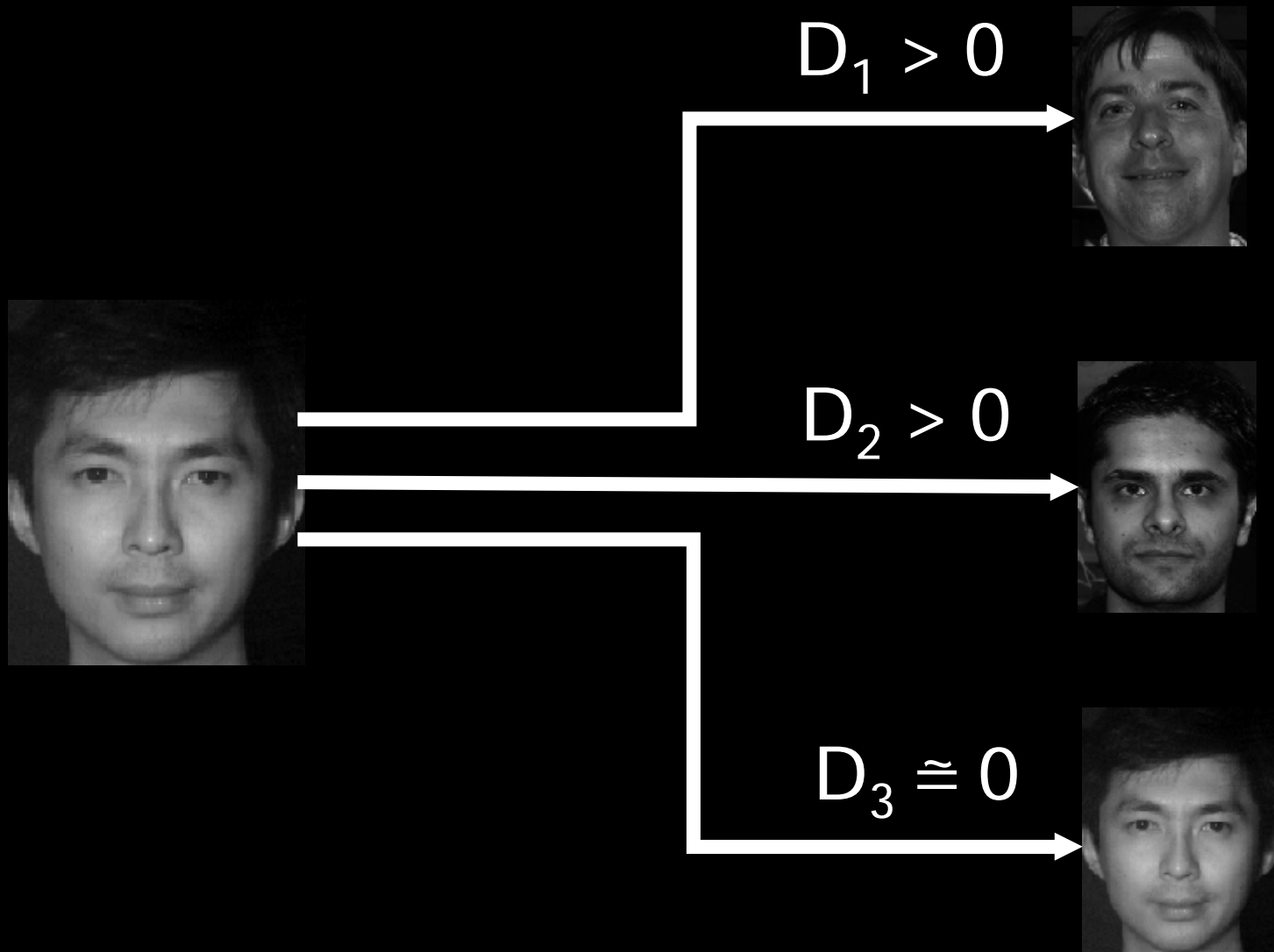
[Sinha and Poggio 2002]

Images as Points in Euclidean Space

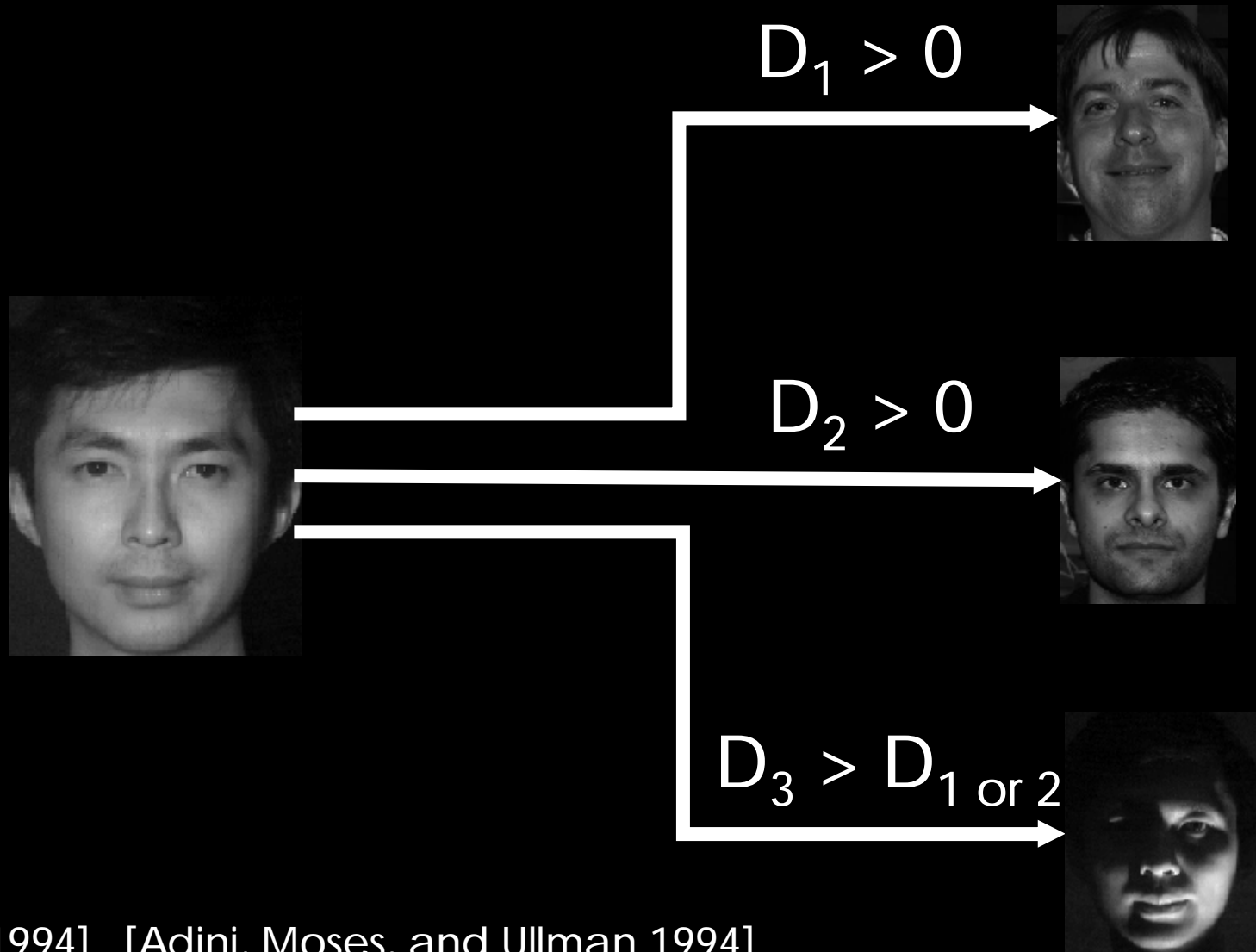


- Let an n -pixel image to be a point in an n -D space, $x \in \mathbb{R}^n$.
- Each pixel value is a coordinate of x .

Face Recognition: Euclidean Distances



Face Recognition: Euclidean Distances



[Hallinan 1994] [Adini, Moses, and Ullman 1994]

Same Person
or
Different People



Same Person
or
Different People



Why is Face Recognition Hard?



Challenges: Image Variability

Short Term

Expression



Pose



Illumination



Long Term

- Facial Hair
- Makeup
- Eyewear
- Hairstyle
- Piercings
- Aging

Illumination Invariants?

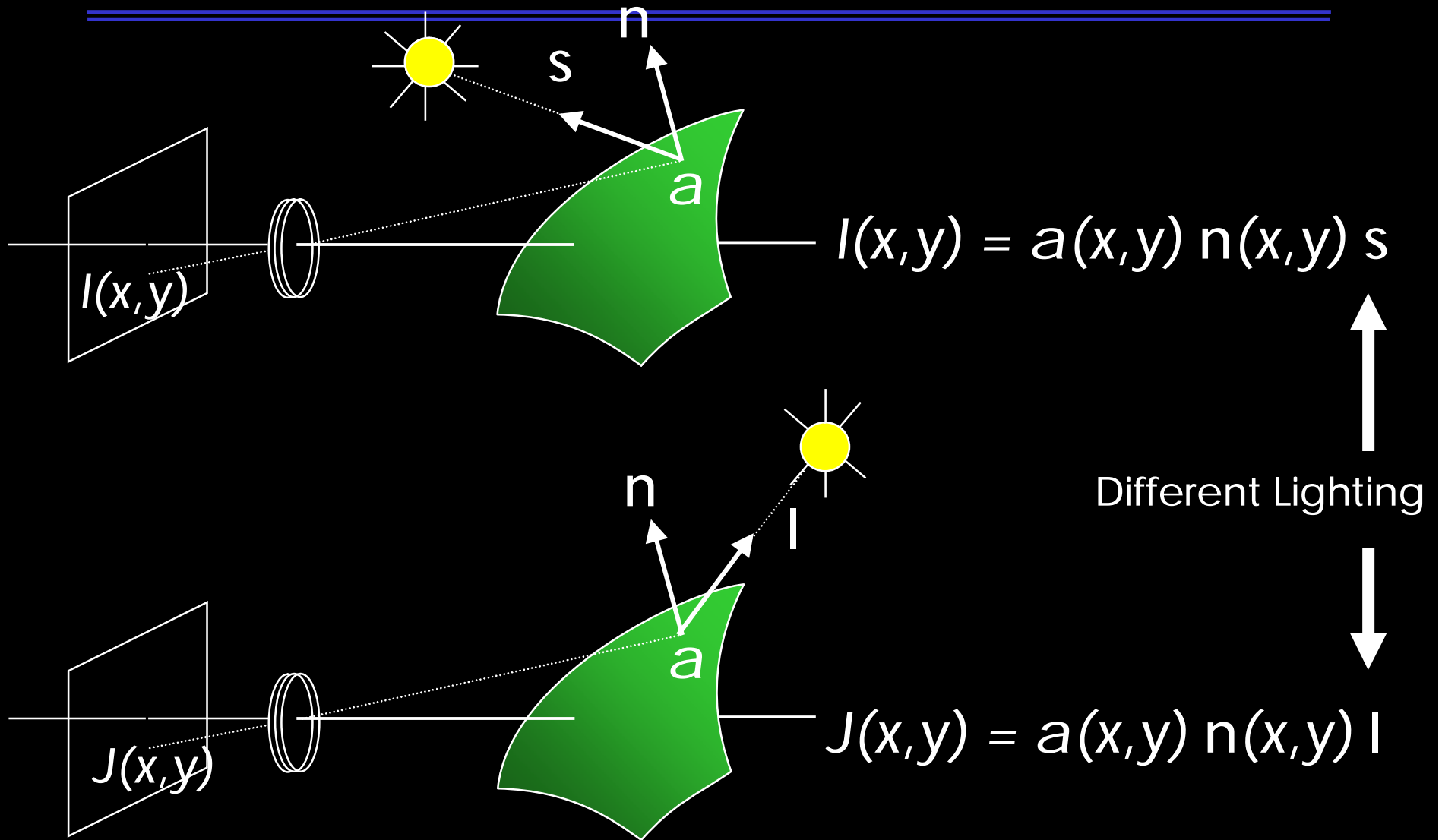
Does there exist a function f s.t.

$$f(\text{img}_1) = f(\text{img}_2) = f(\text{img}_3) = a$$

and

$$f(\text{img}_4) = f(\text{img}_5) = f(\text{img}_6) = b \quad ?$$

Can Any Two Images Arise from a Single Surface?



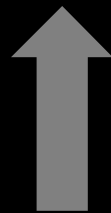
The Surface PDE

$$I(x,y) = a(x,y) n(x,y) s$$

$$J(x,y) = a(x,y) n(x,y) l$$



$$(I l - J s) n = 0$$



Nonlinear PDE



Linear PDE

Non-Existence Theorem for Illumination Invariants

Illumination invariants for 3-D objects **do not exist**.

This result *does not ignore* attached and cast shadows, as well as surface interreflection.

[Chen, Belhumeur, and Jacobs 2000]

Geometric Invariants?

Does there exist a function f s.t.

$$f(\text{img1}) = f(\text{img2}) = f(\text{img3}) = a$$

and

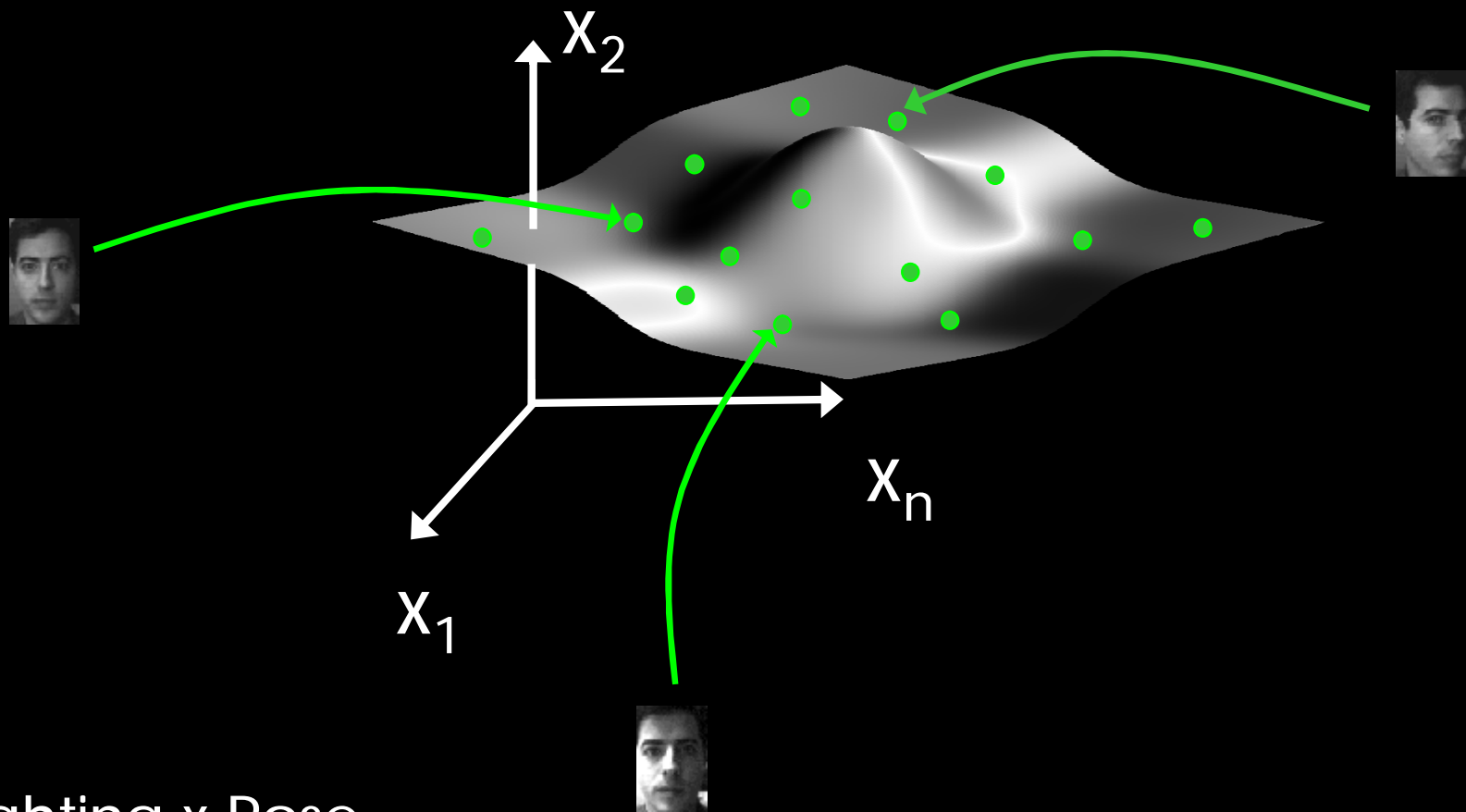
$$f(\text{img4}) = f(\text{img5}) = f(\text{img6}) = b ?$$

Non-Existence Theorem for Geometric Invariants

Geometric invariants for rigid transformations of 3-D objects viewed under perspective projective projection **do not exist**.

[Burns, Weiss, and Riseman 1992]

Image Variability: Appearance Manifolds



Lighting x Pose

[Murase and Nayar 1993]

Modeling Image Variability

Can we model illumination and pose variability in images of a face?

Yes, if we can determine the shape and texture of the face. But how?

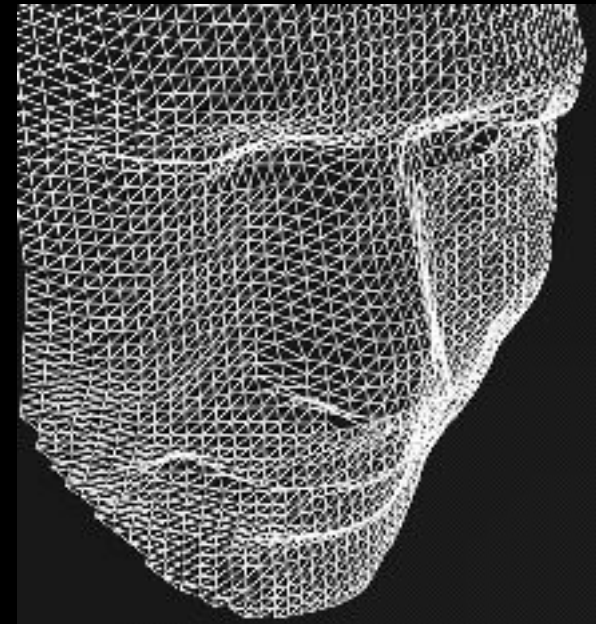
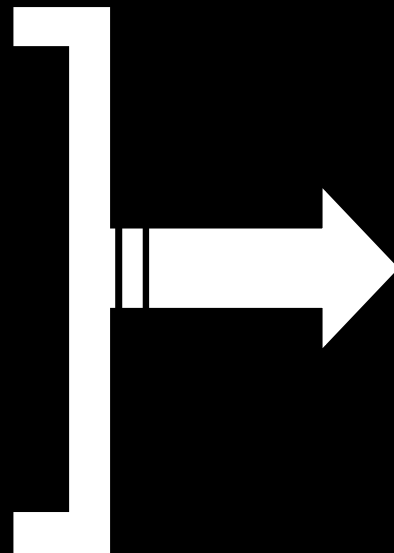
Modeling Image Variability: 3-D Faces

Laser Range Scanners

Stereo Cameras

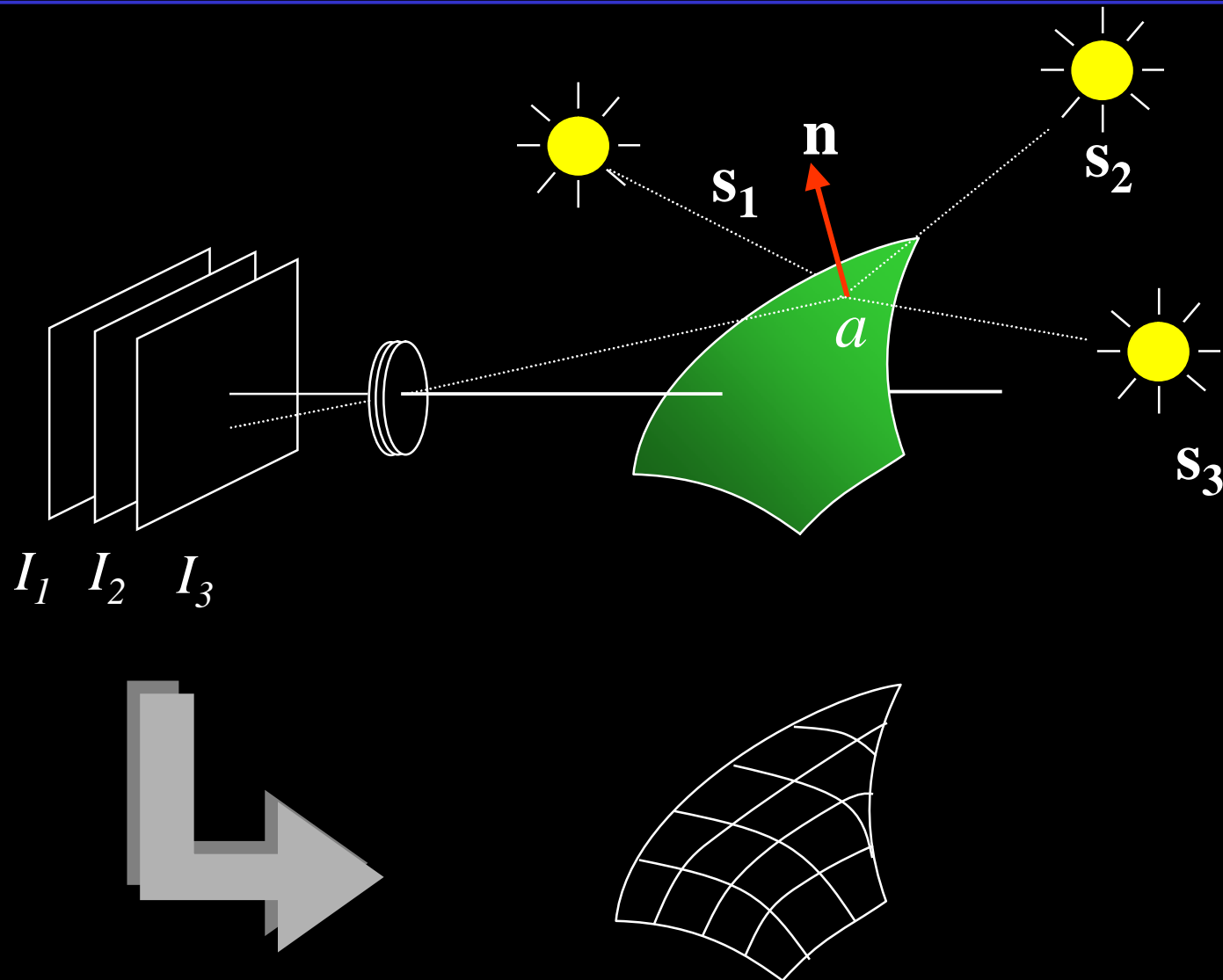
Structured Light

Photometric Stereo



[Atick, Griffin, Redlich 1996] [Georghiades, Belhumeur, Kriegman 1996] [Blanz and Vetter 1999] [Zhao and Chellapa 1999] [Kimmel and Sapiro 2003] [Geometrix 2001] [MERL 2005]

Illumination Variation Reveals Object Shape



[Woodham 1984]

Illumination Movie



Illumination Movie

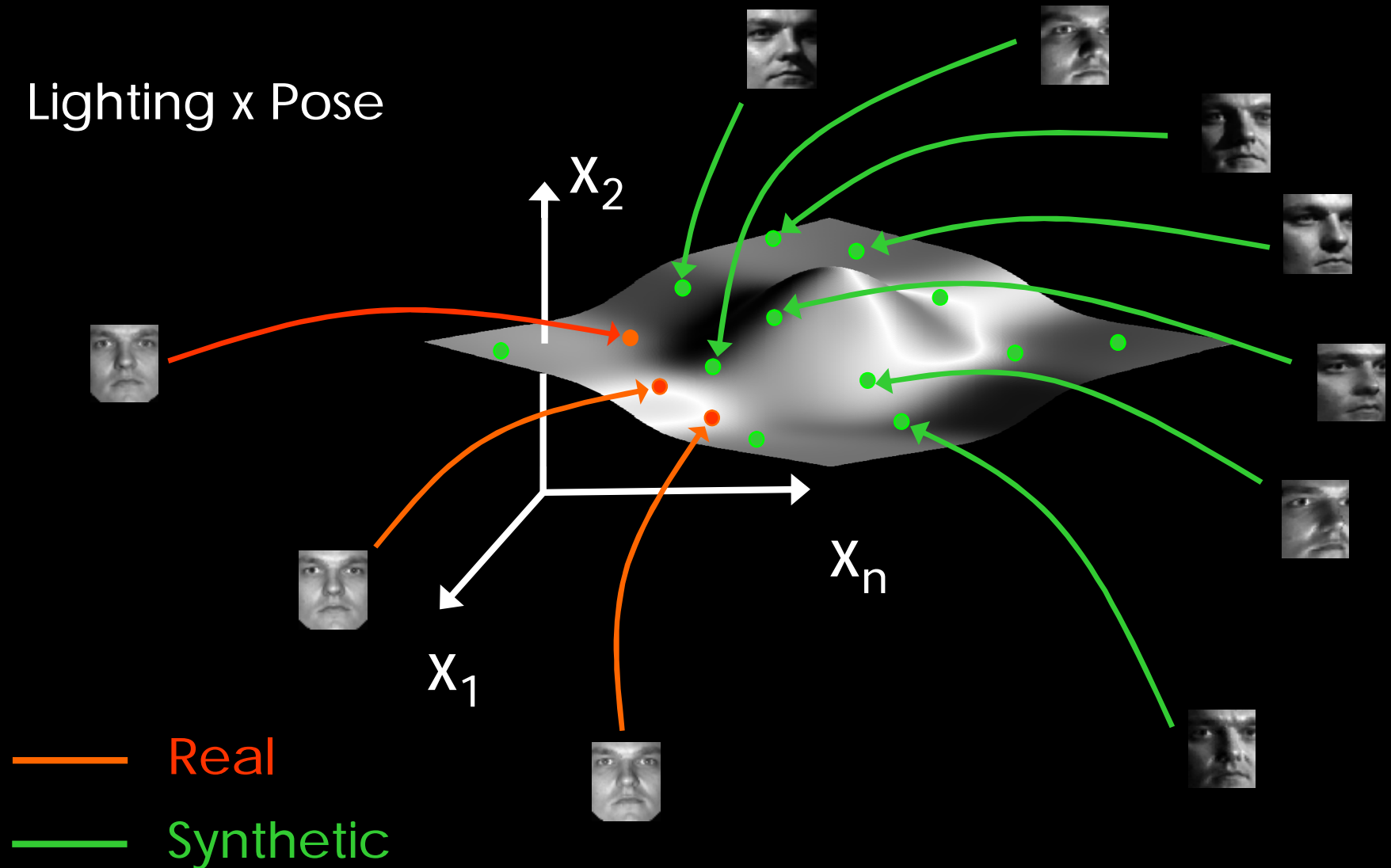
Shape Movie



Shape Movie

Image Variability: From Few to Many

Lighting x Pose

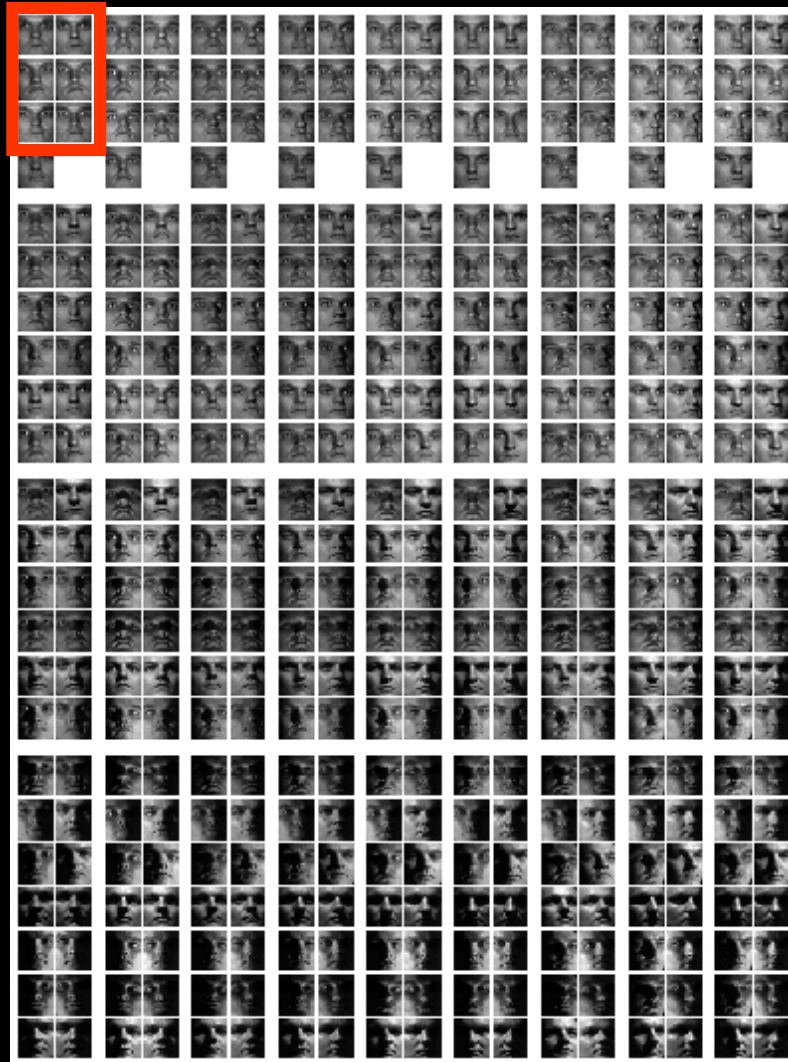


[Georghiades, Belhumeur, and Kriegman 1999]

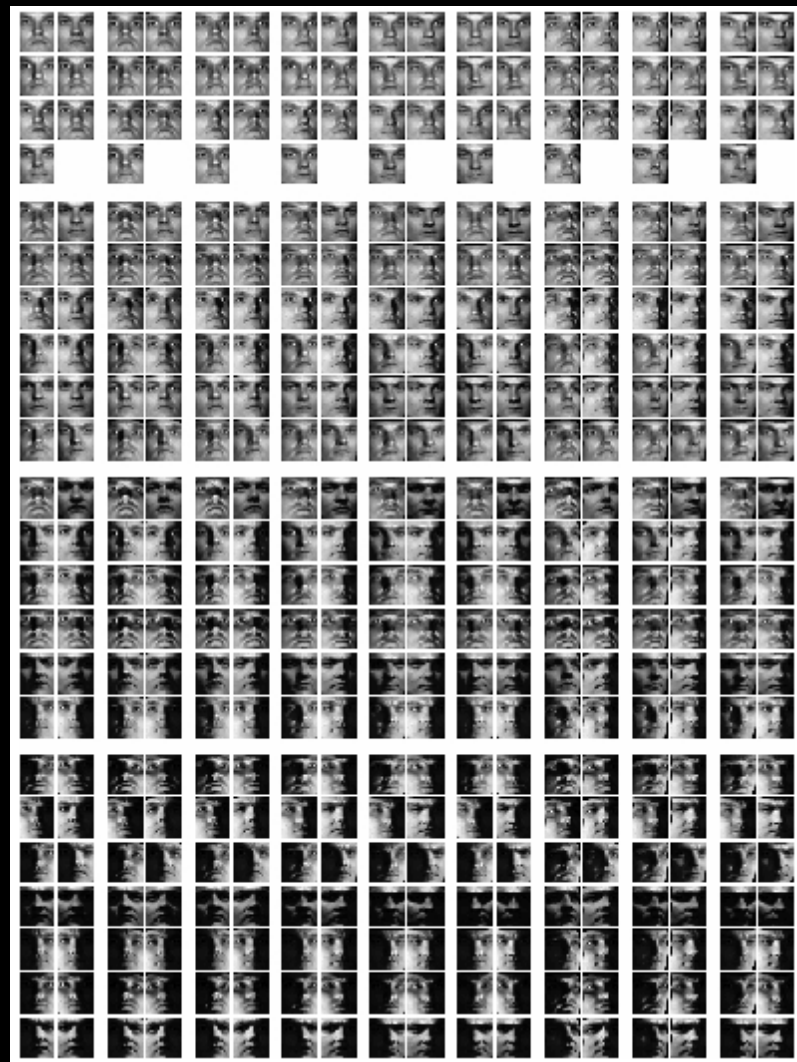
Illumination Dome



Real vs. Synthetic



Real



Synthetic

Real vs. Synthetic

Real

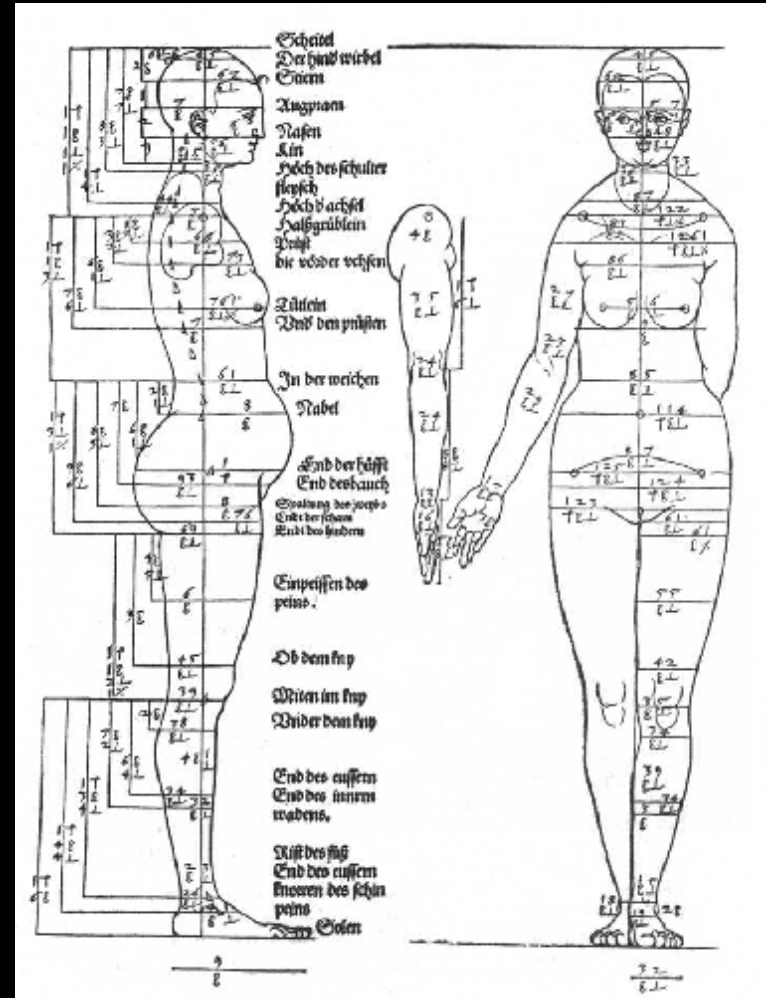
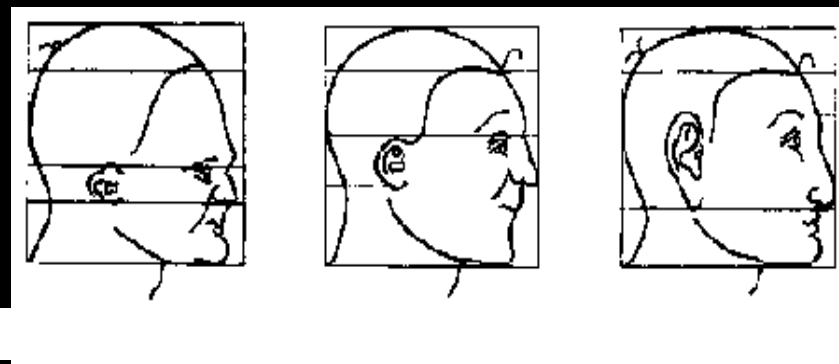
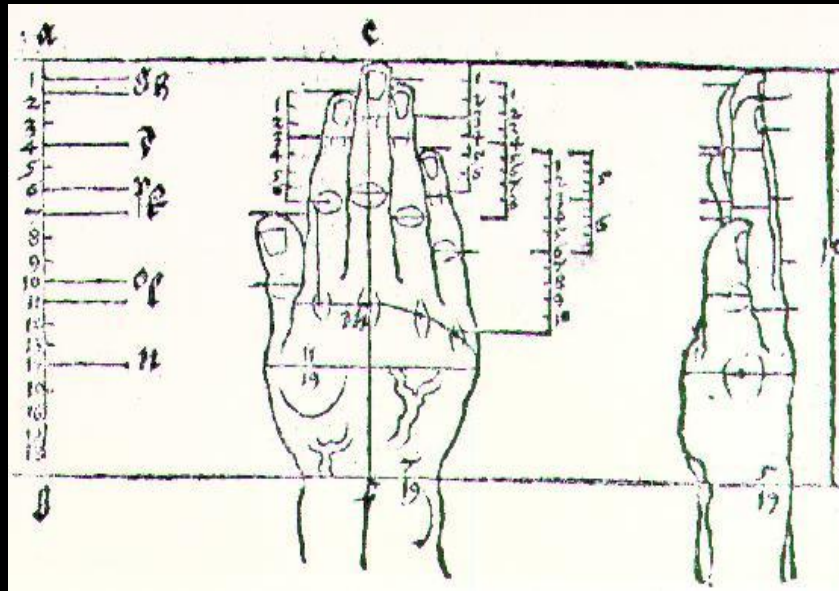


Synthetic



A Step Back in Time

Albrecht Dürer, "Four Books on Human Proportion" (1528)



D'arcy Thompson, "On Growth and Form" (1917)

1062 THE THEORY OF TRANSFORMATIONS (cont.)

which fossils are subject (as we have seen on p. 871) as the result of shearing stresses in the solid rock.

Fig. 519 is an outline diagram of a typical Searoid fish. Let us deform its rectangular coordinates into a system of (approximately) coaxial circles, as in Fig. 520, and then filling into the new system,

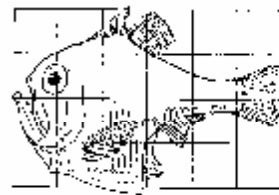


Fig. 519. *Apogonoides affinis*.

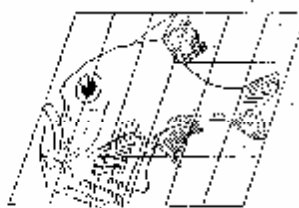


Fig. 518. *Sarcophaga Cyprina*.

space by space and point by point, our former diagram of *Sarcophaga*, we obtain a very good outline of an allied fish, belonging to a neighbouring family, of the genus *Pomacentrus*. This case is all the more interesting, because (for the only of our *Pomacentrus* there are striking colour bands, which correspond in direction very closely

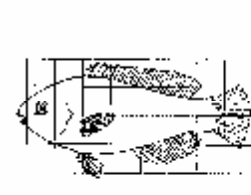


Fig. 510. *Sarcophaga* sp.



Fig. 520. *Pomacentrus*.

to the lines of our new curved ordinates. In like manner, the still more bizarre outlines of other fishes of the same family of Chaetodonts will be found to correspond to very slight modifications of similar coordinates; in other words, to small variations in the values of the constants of the coaxial curves.

Figs. 521-524 have represented another series of Asmuthodontes, not very distinctly related to the foregoing. If we

xvii] THE COMPARISON OF RELATED FORMS. 1063

start this series with the figure of *Polyprion*, in Fig. 521, we see that the outlines of *Pseudopomacentrus* (Fig. 522) and of *Helicetes* or *Sariparus* (Fig. 523) are easily derived by substituting a system

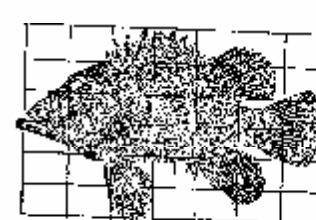


Fig. 521. *Polyprion*.

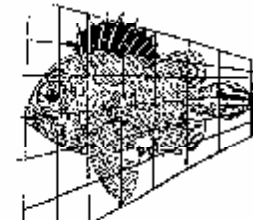


Fig. 522. *Pseudopomacentrus affinis*.

of triangular, or radial, coordinates for the rectangular ones in which we had inscribed *Polyprion*. The very curious fish *Antigonia caprea*, an oceanic relative of our own bou-fish, conforms closely to the peculiar deformation represented in Fig. 524.

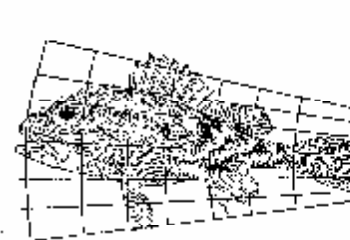


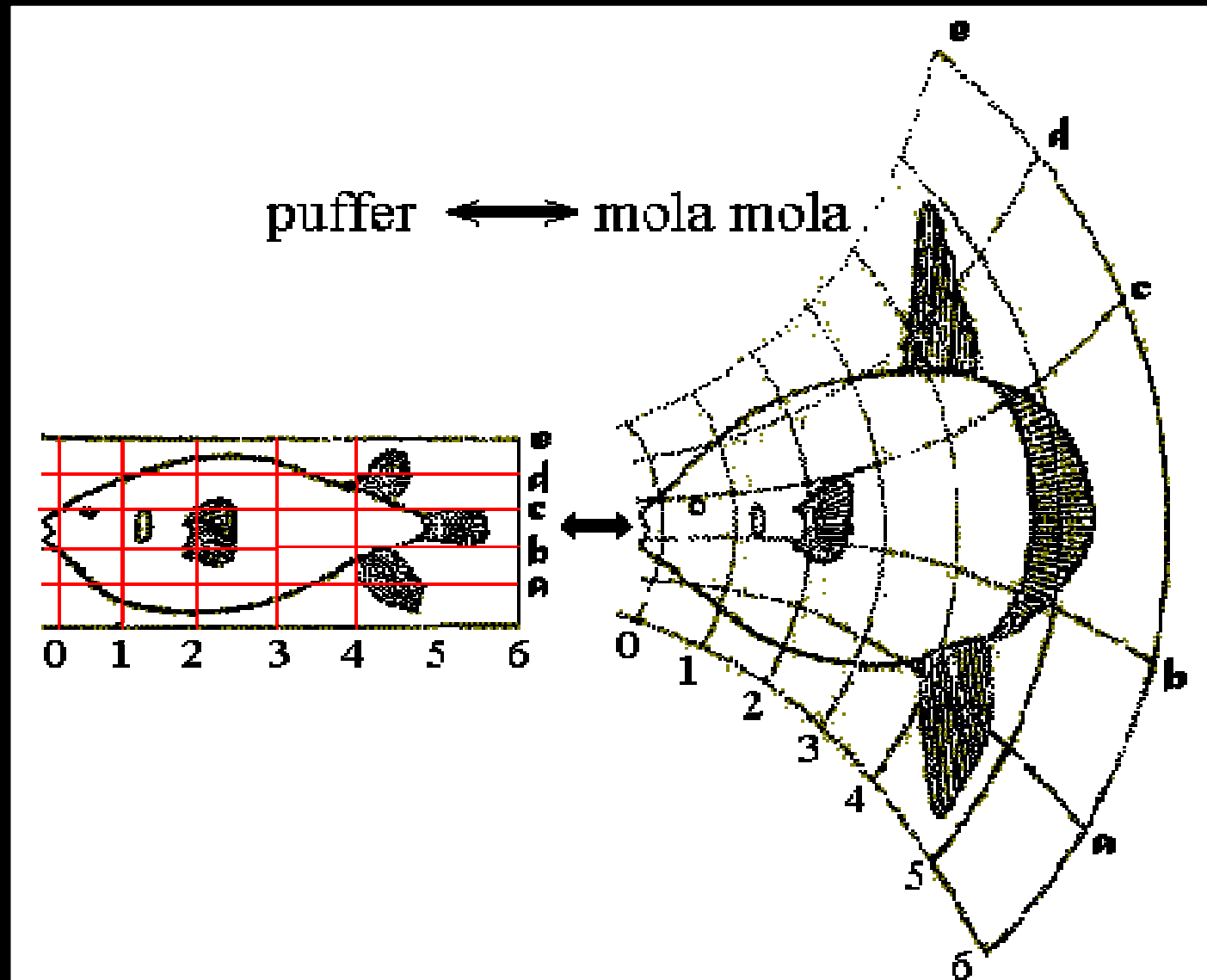
Fig. 523. *Gerygone* sp.



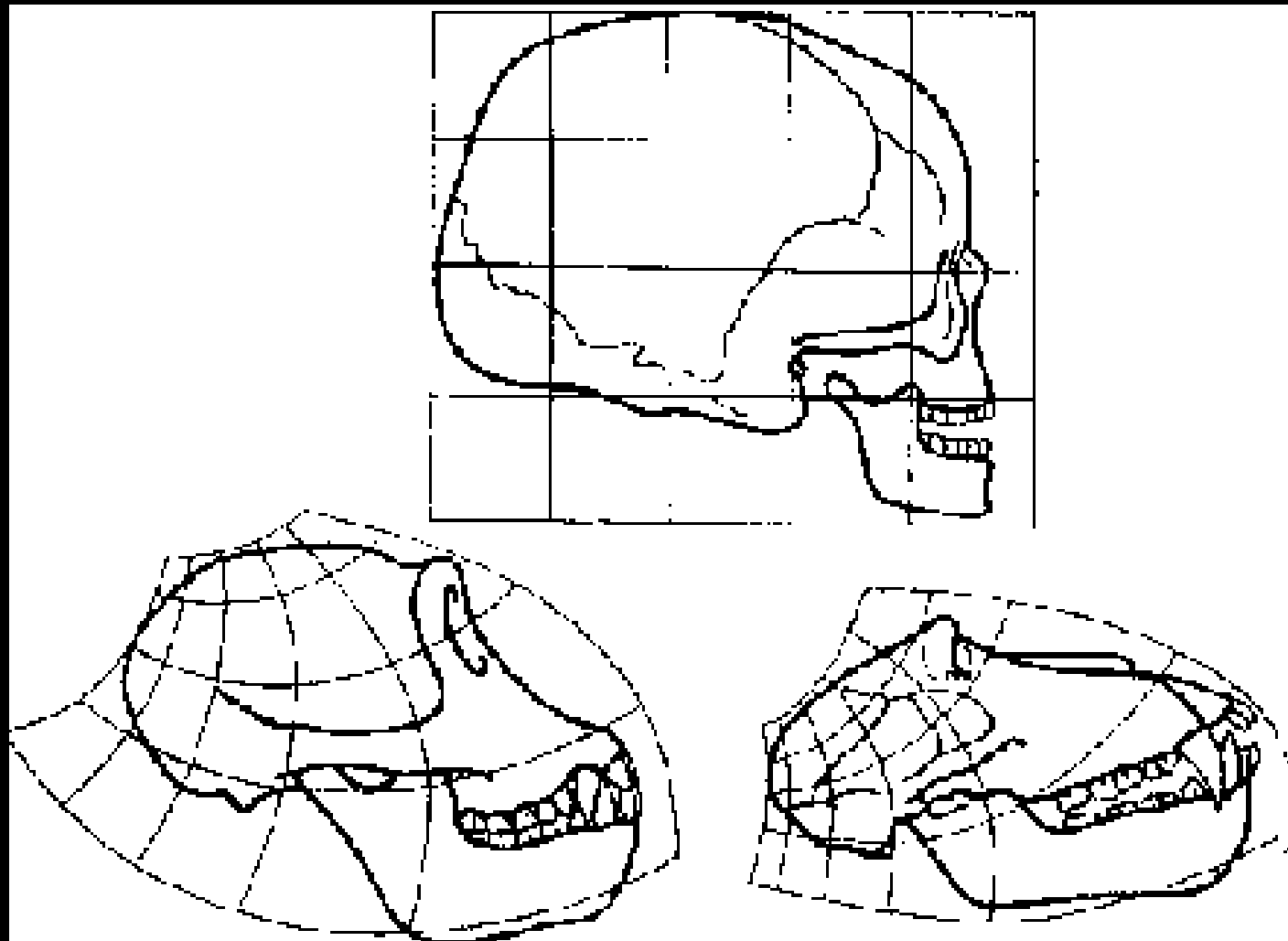
Fig. 524. *Antigonia caprea*.

Fig. 525 is a common, typical *Diodon* or porcupine-fish, and in Fig. 526 I have deformed its vertical coordinates into a system of concentric circles, and its horizontal coordinates into a system of curves which, approximately and provisionally, are made to resemble

D'arcy Thompson, "On Growth and Form" (1917)



D'arcy Thompson, "On Growth and Form" (1917)

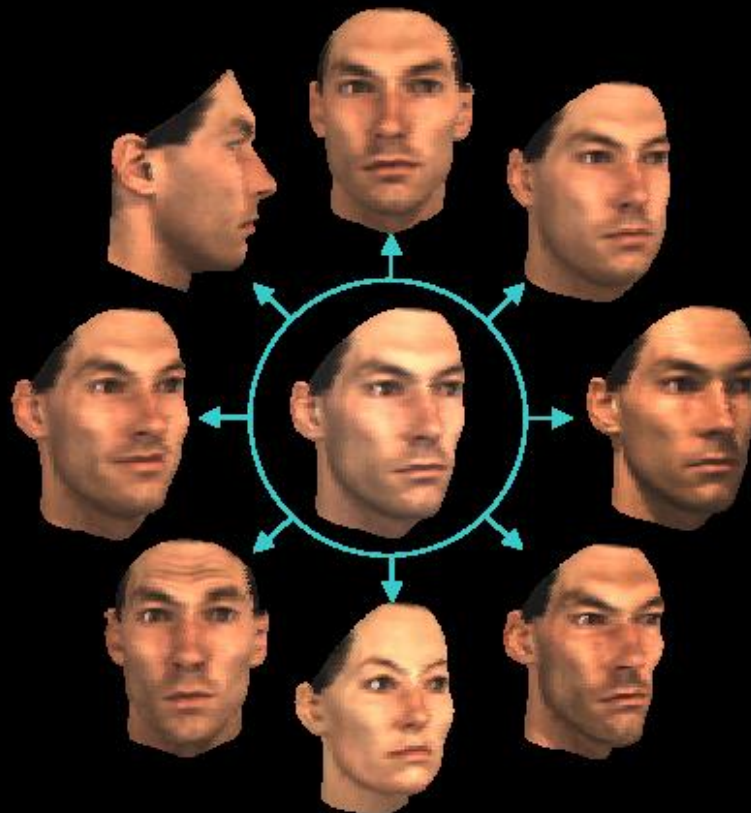


Skulls of a human, a chimpanzee and a baboon
and transformations between them

But what if we could?

From a single image

- Novel views
- Novel expressions
- Synthesis of siblings
- Change of illumination
- Variations of body weight



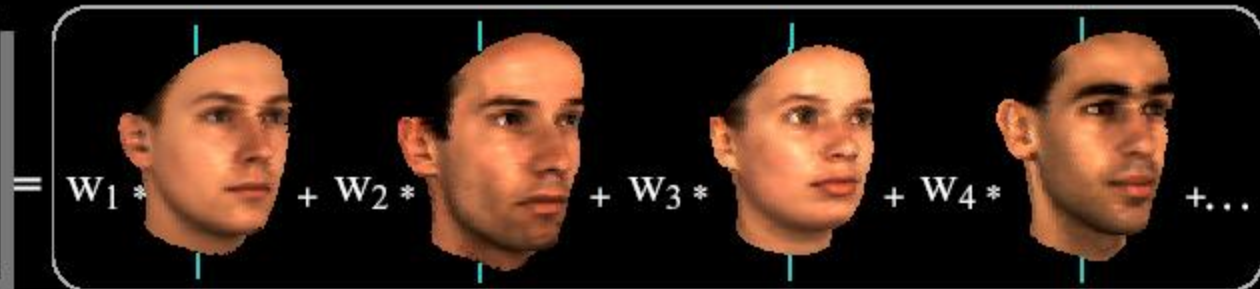
[Blanz and Vetter 1999, 2003]

Building a Morphable Face Model

2D Image

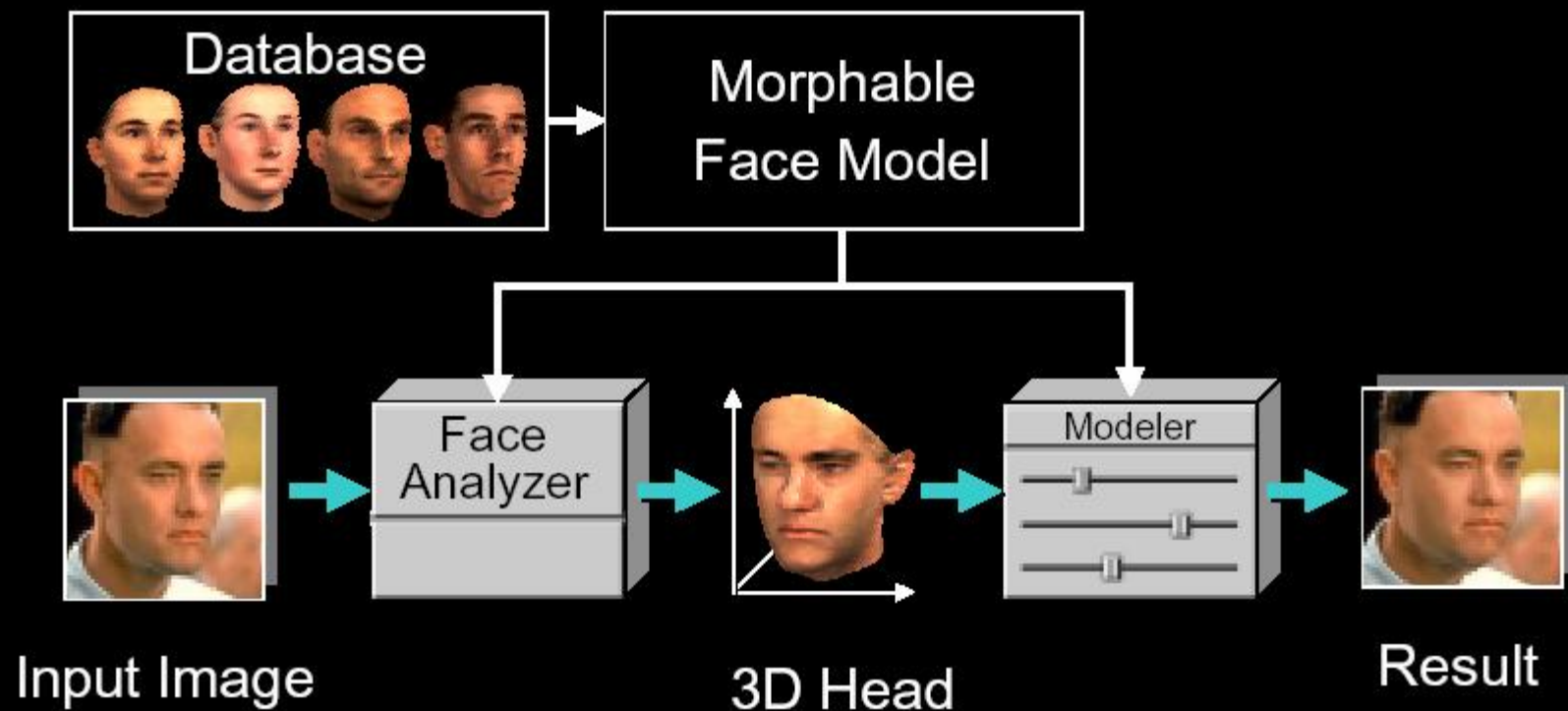


3D Face Models

$$= w_1 * \text{Model}_1 + w_2 * \text{Model}_2 + w_3 * \text{Model}_3 + w_4 * \text{Model}_4 + \dots$$


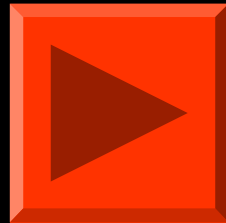
[Blanz and Vetter 1999, 2003]

3-D Morphable Models: Semi-Automatic



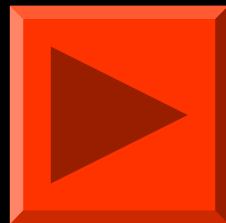
[Blanz and Vetter 1999, 2003]

Building Morphable Face Models



[Blanz and Vetter 1999, 2003]

Fitting Morphable Face Models



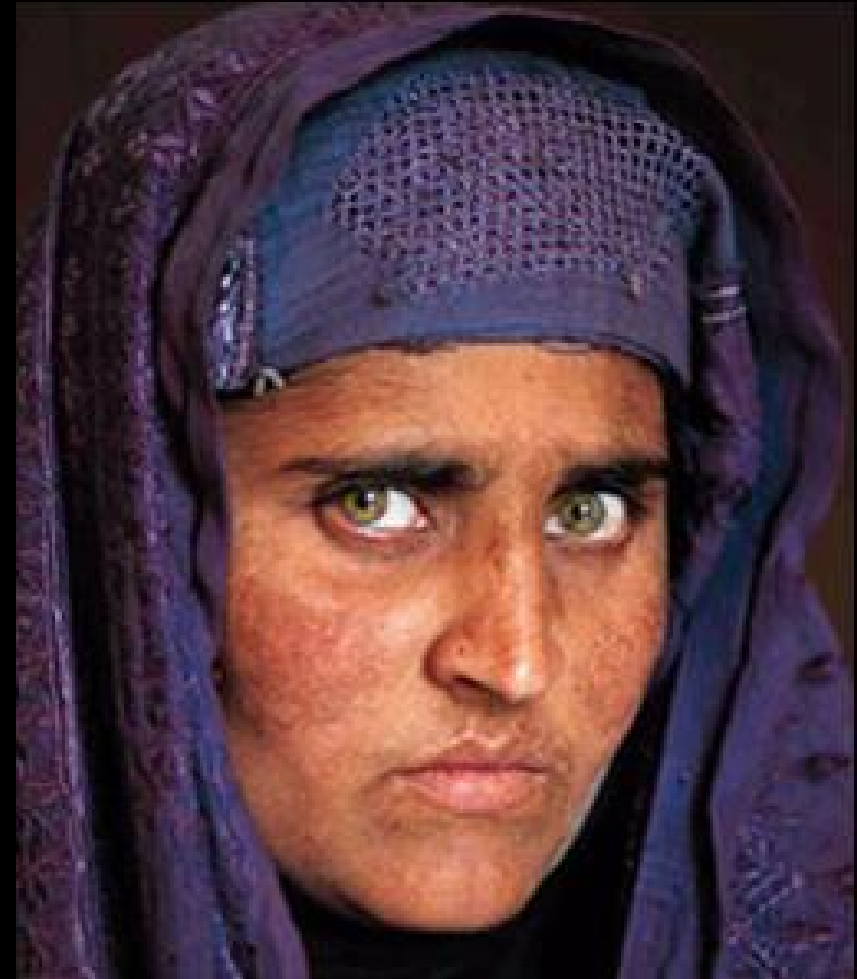
[Blaaz and Vetter 1999, 2003]

National Geographic 1984 and 2002

1985



2002



Identity Confirmed by IRIS



=



[Daugman 2002]