

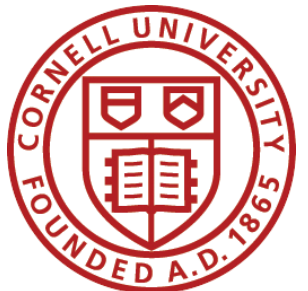
# Correct-by-construction synthesis for smart manufacturing

Hadas Kress-Gazit

Mechanical and Aerospace Engineering, Cornell University

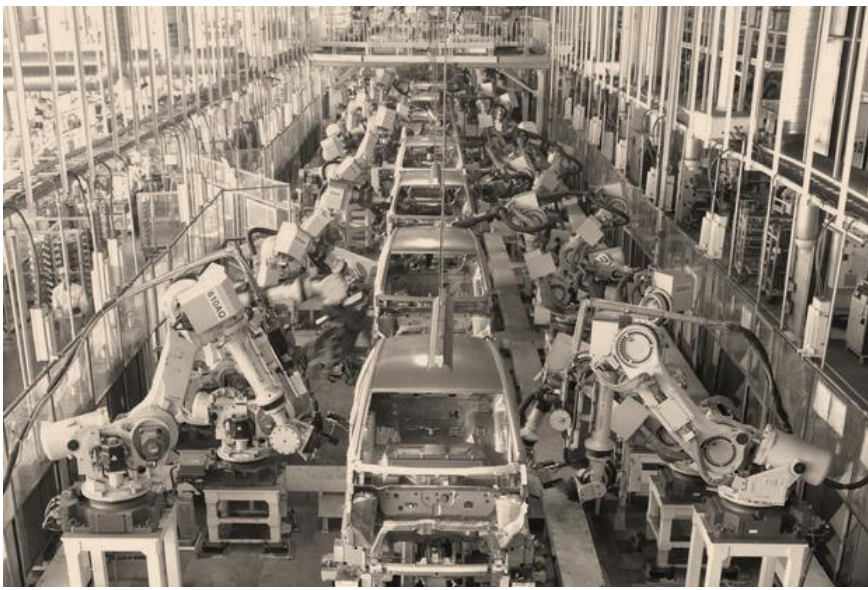
[hadaskg@cornell.edu](mailto:hadaskg@cornell.edu)

<http://verifiablerobotics.com/>





<https://iptmajor.weebly.com/automated-assembly-line-robotic-arms.html>



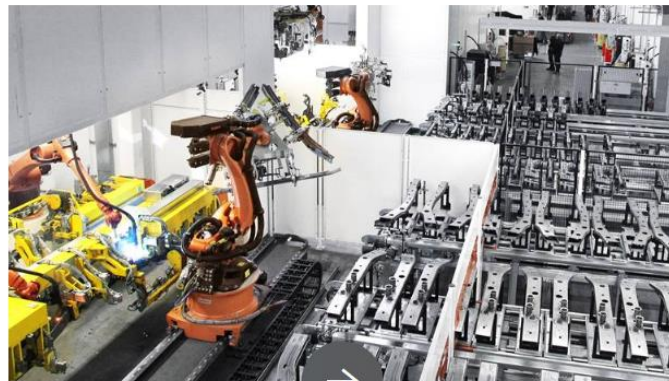
### Standardized manufacturing cells

We supply future-oriented and highly automated manufacturing cells based on standardized and flexible cell concepts.

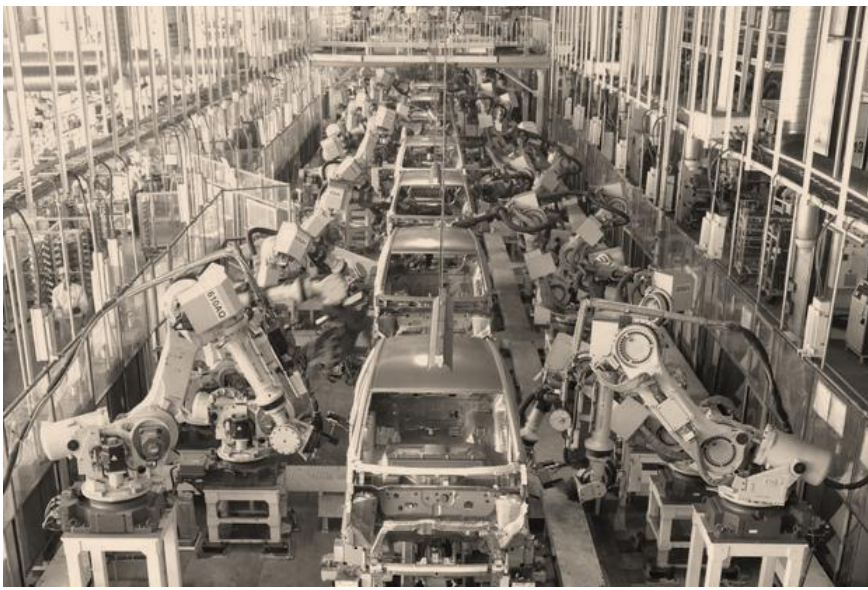


### Customized manufacturing cells

As a competent partner we supply you with manufacturing cells configured for your special production requirements.







Rethink robotics



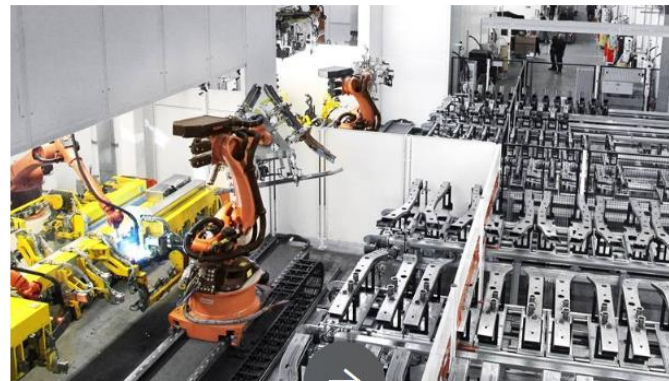
### Standardized manufacturing cells

We supply future-oriented and highly automated manufacturing cells based on standardized and flexible cell concepts.



### Customized manufacturing cells

As a competent partner we supply you with manufacturing cells configured for your special production requirements.



Oliver Berg | picture-alliance | dpa | AP Images

Flexible  
Customizable  
Programmable  
Safe



<https://www.pengate.com/lift-trucks/used-forklifts>





<https://www.pengate.com/lift-trucks/used-forklifts>

<https://www.dcvelocity.com/articles/20170718-nine-ways-to-boost-warehouse-performance-and-cut-turnover/>

EXHIBIT 2

Employee turnover (both full-time and temp workers)

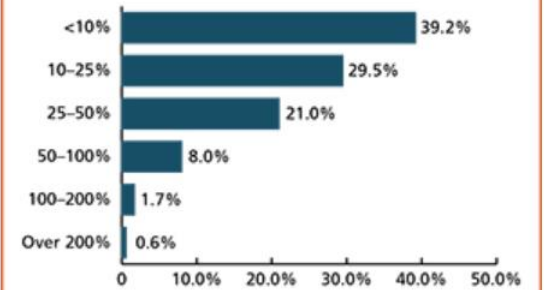


EXHIBIT 3

Employee turnover for temps

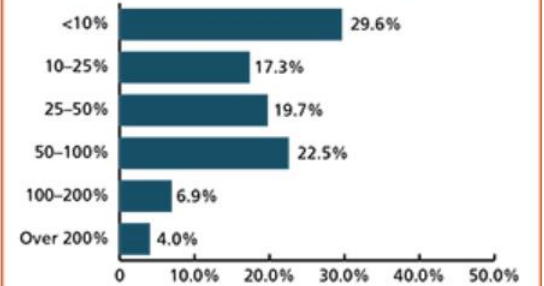
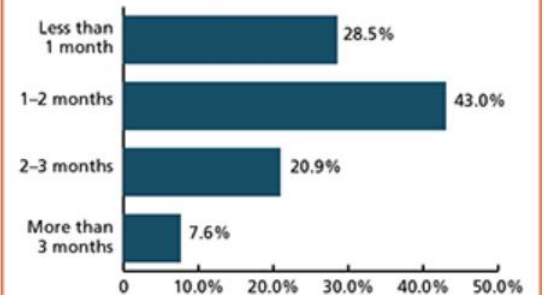


EXHIBIT 4

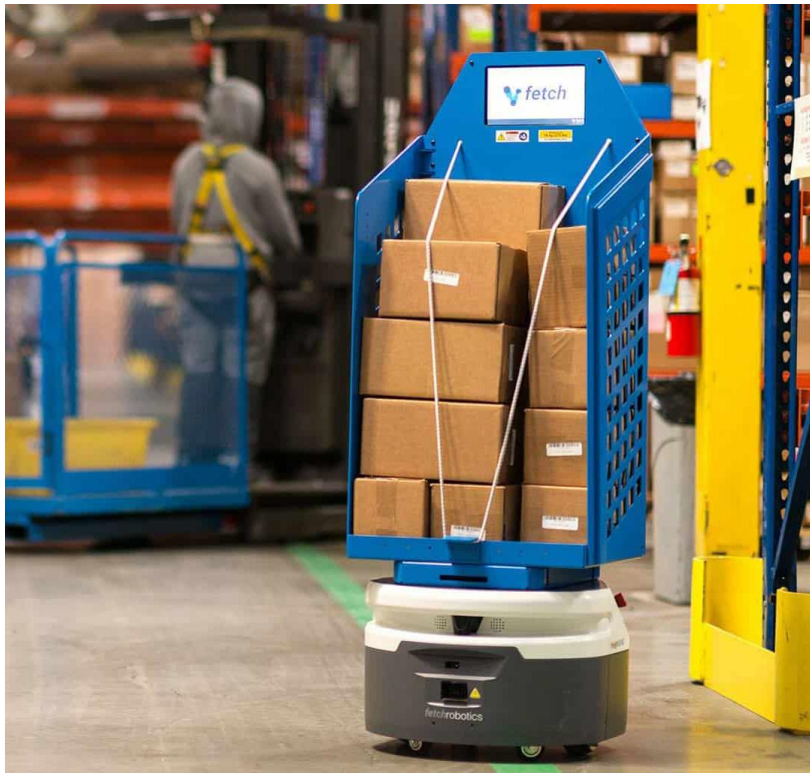
Length of time needed to bring a new employee up to speed







Raymond



Fetch robotics

Berkshire Grey

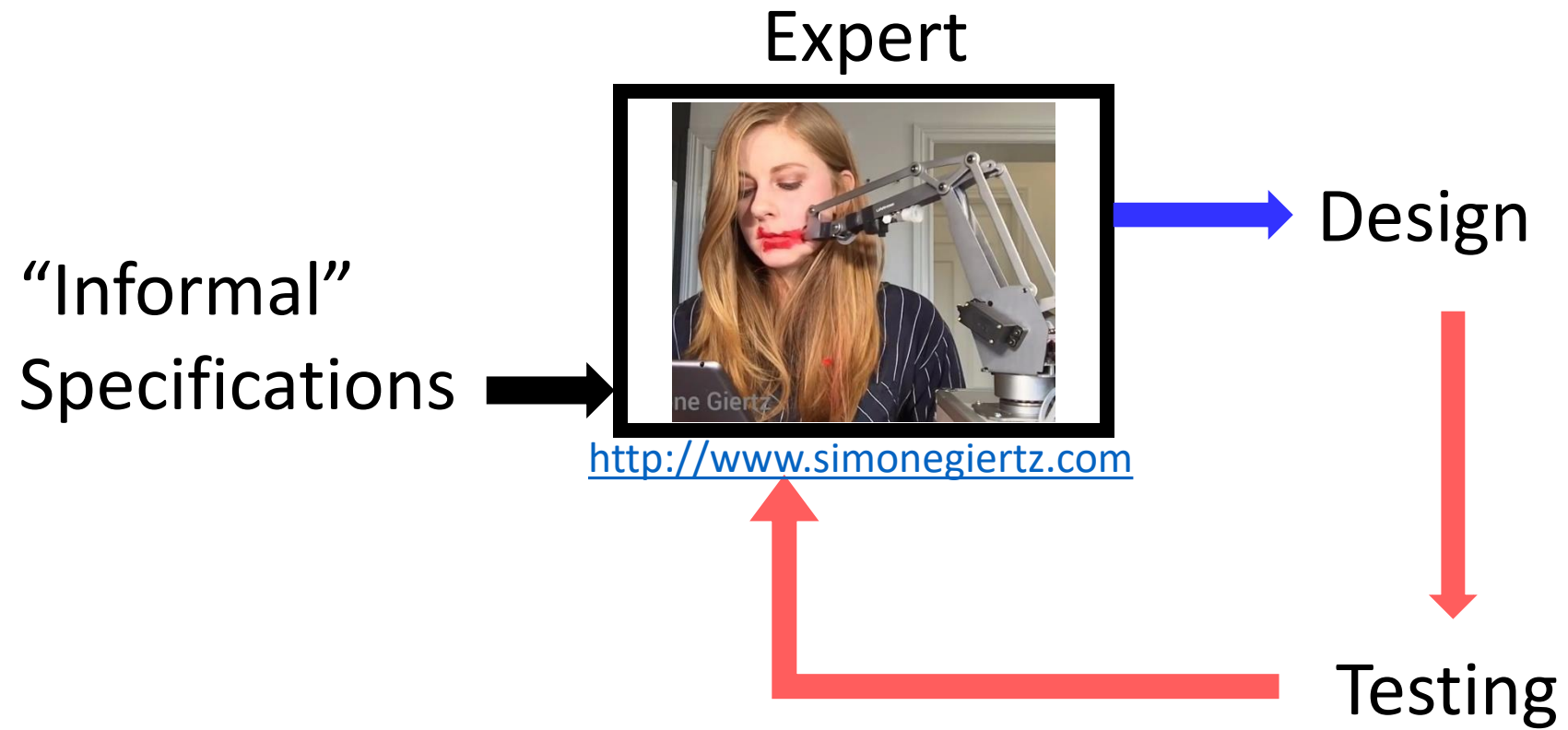


OTTO motors

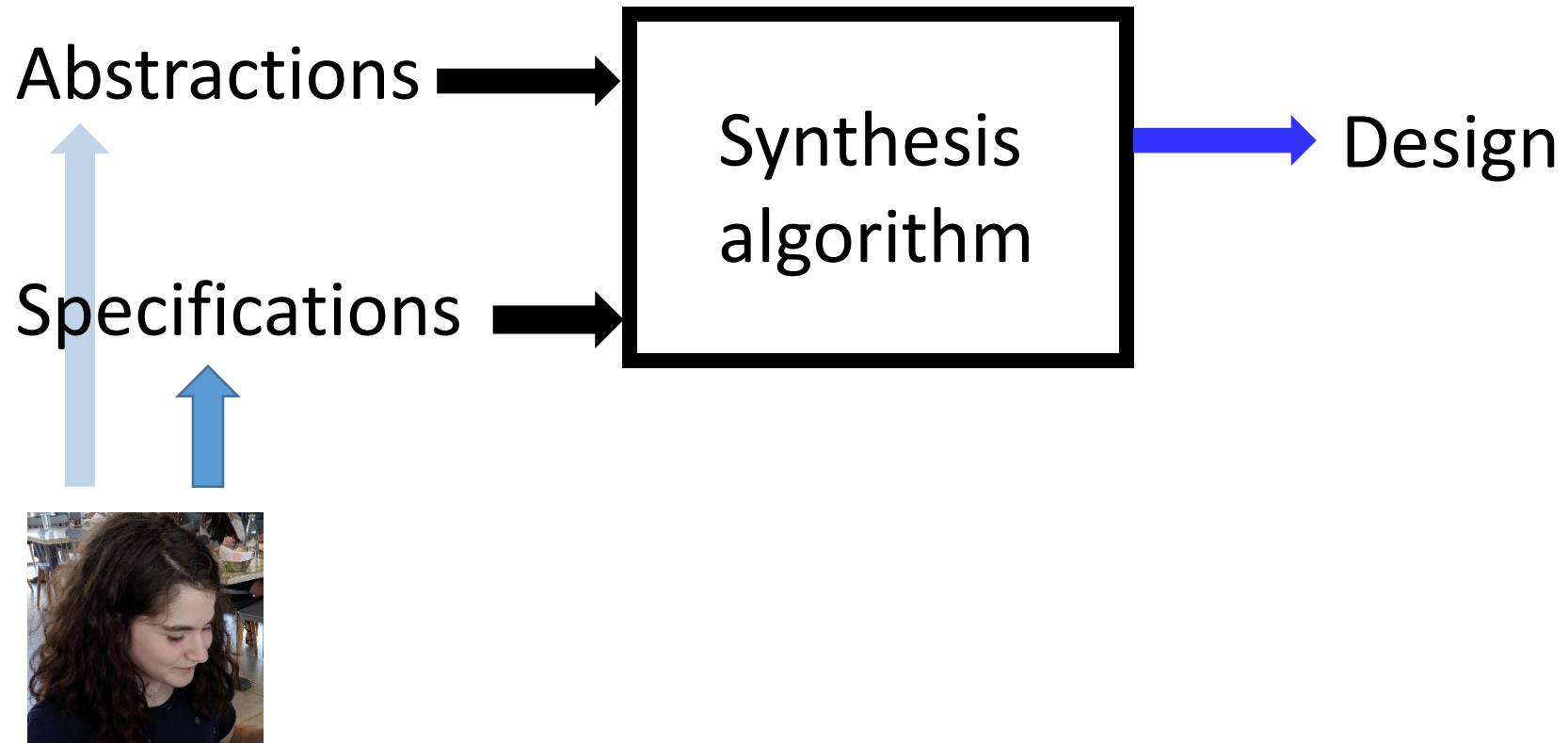


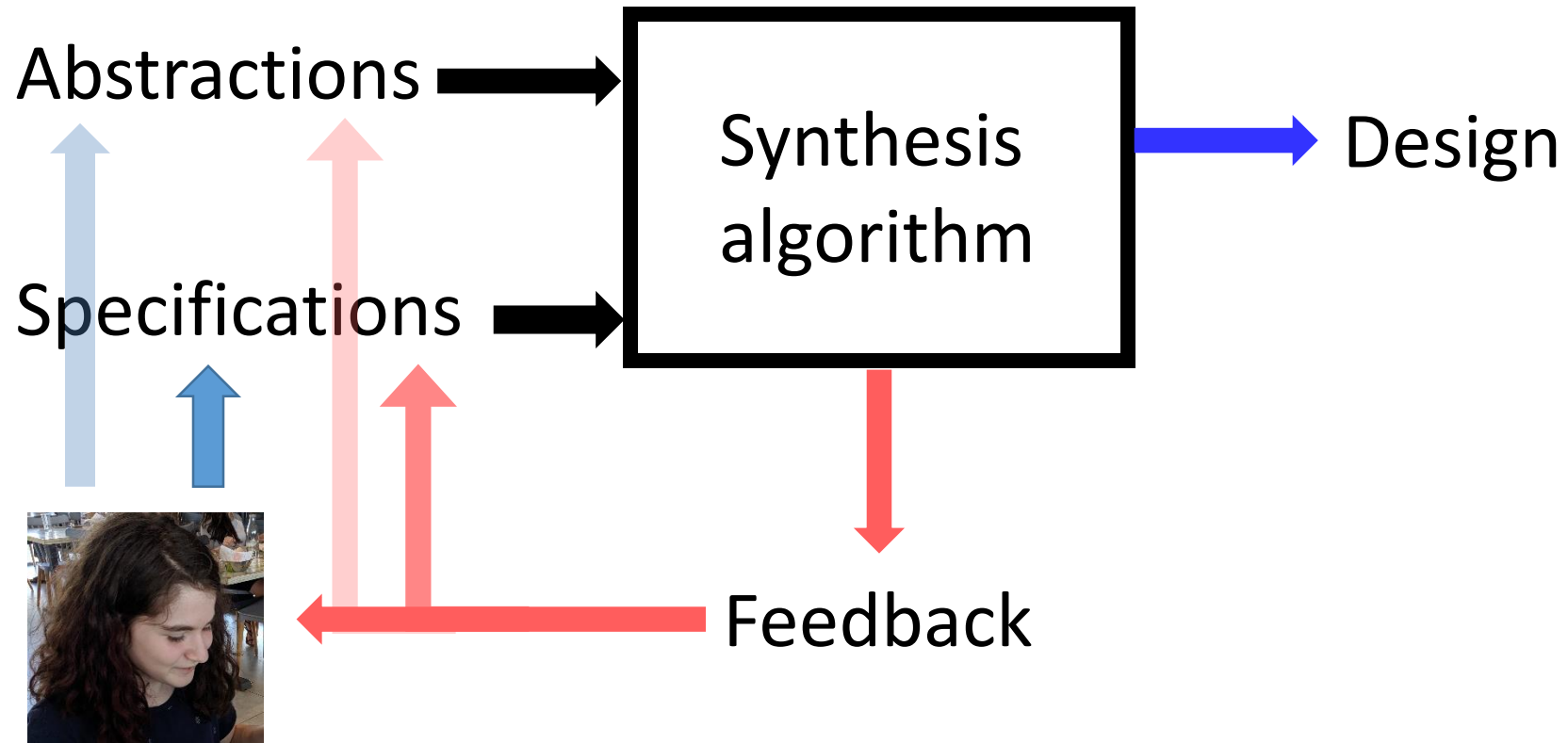
Flexible  
Customizable  
Programmable  
Safe

Automated



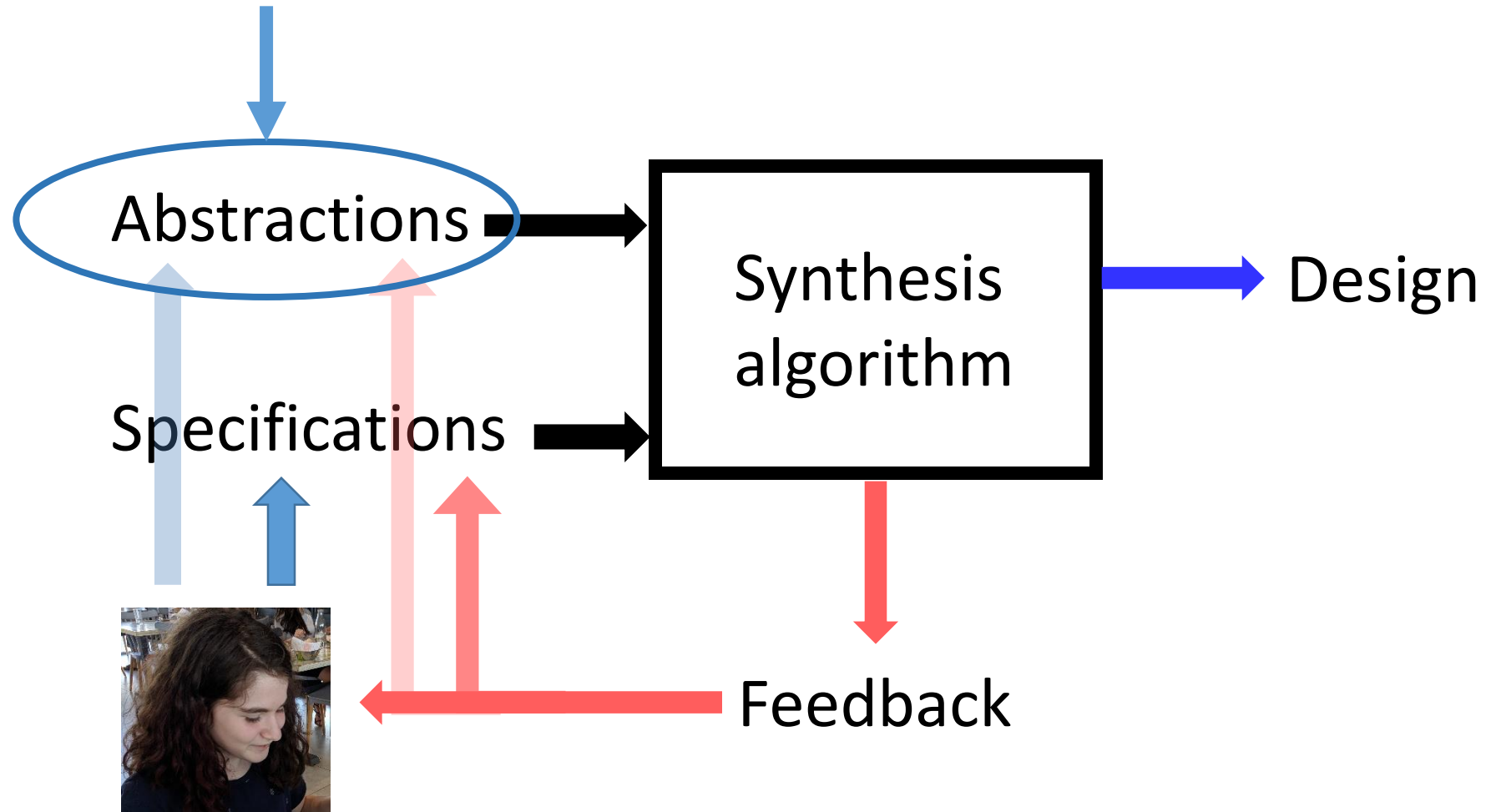


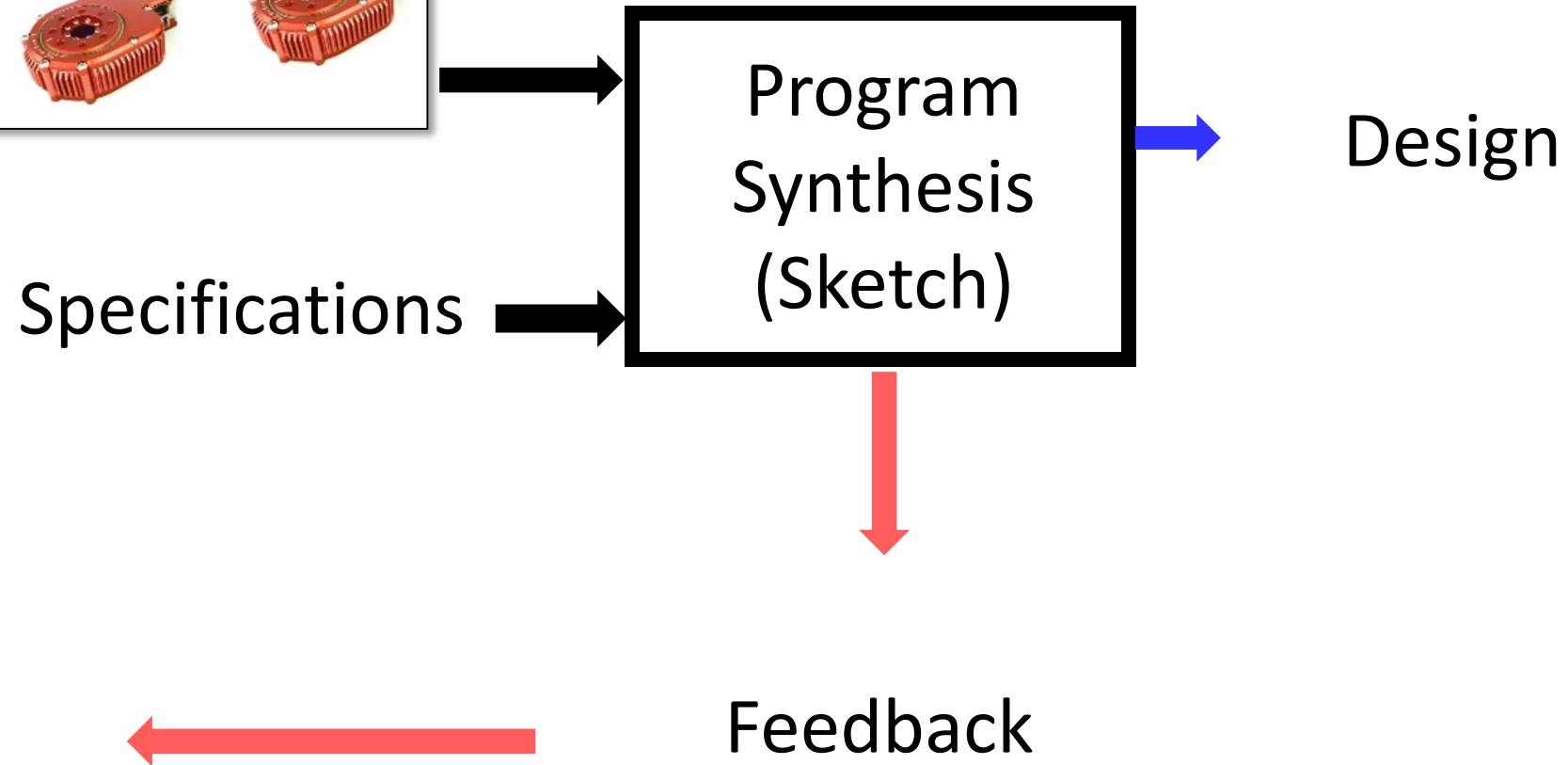




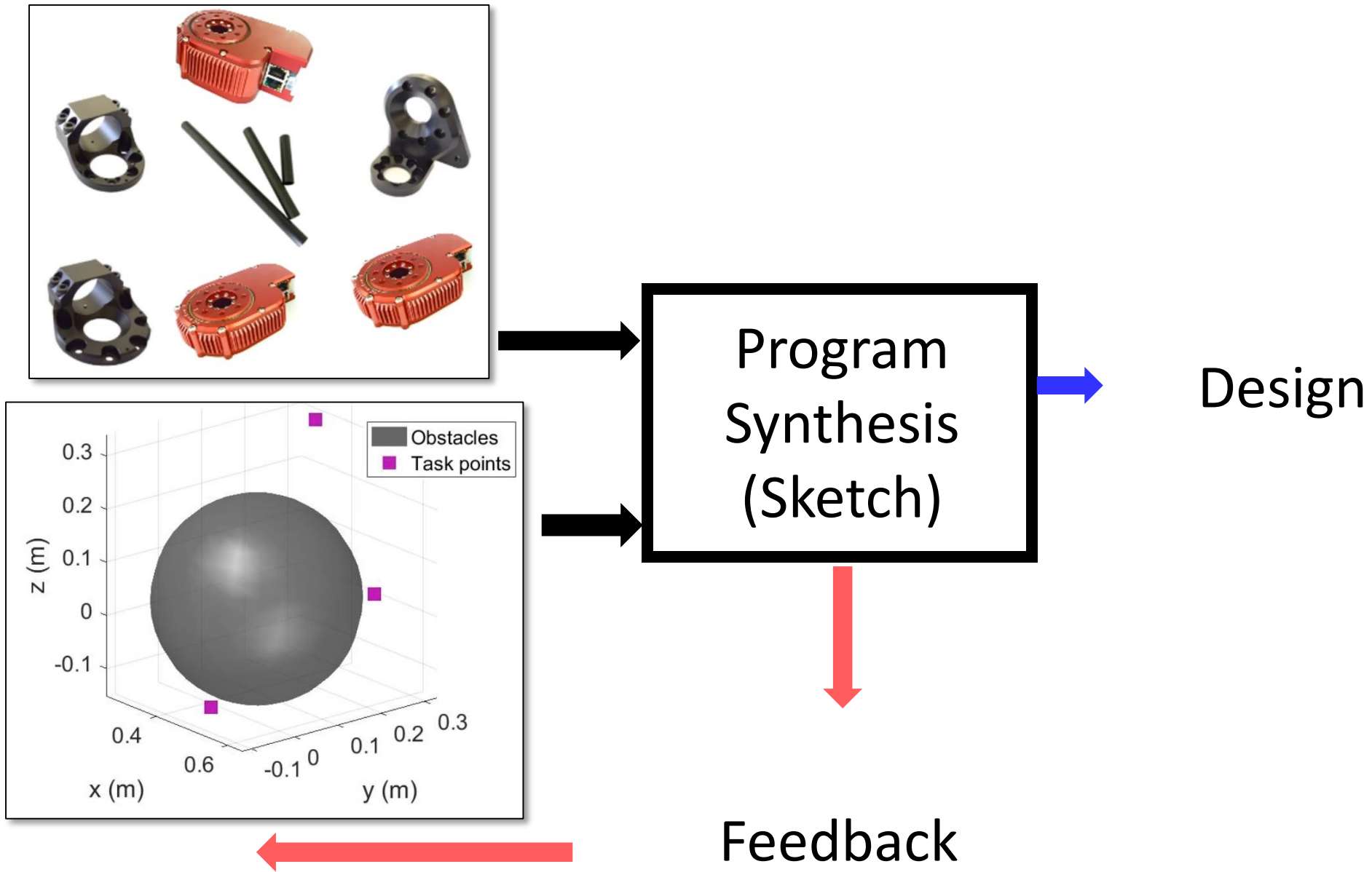


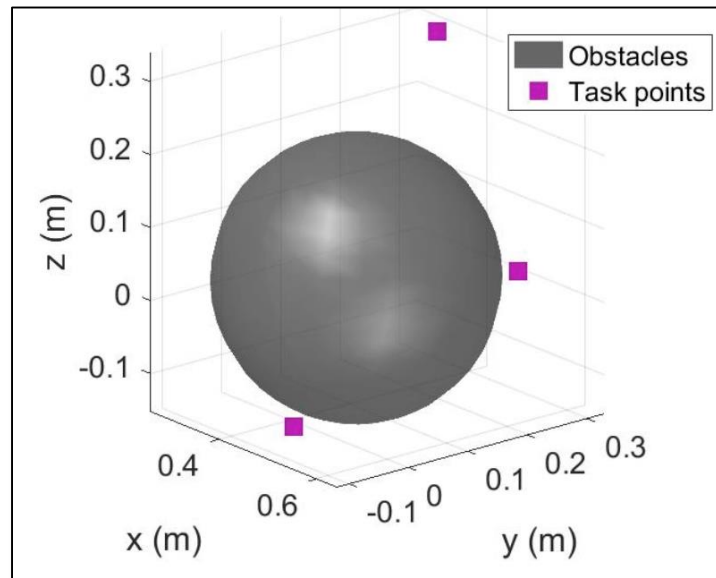
Prof. Zeilinger's and Dr. Matthews' talks!



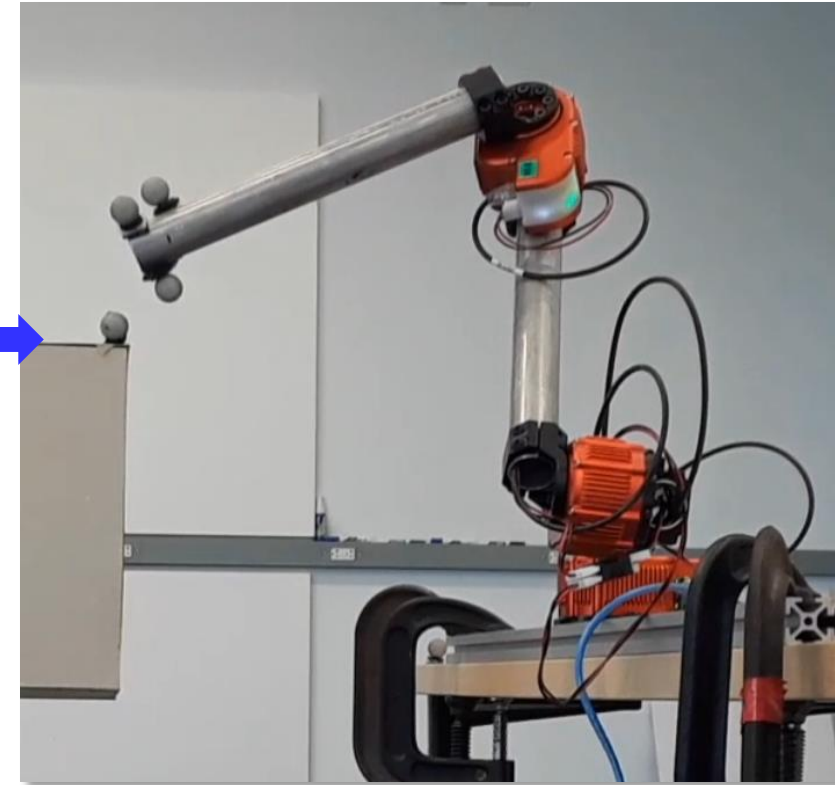








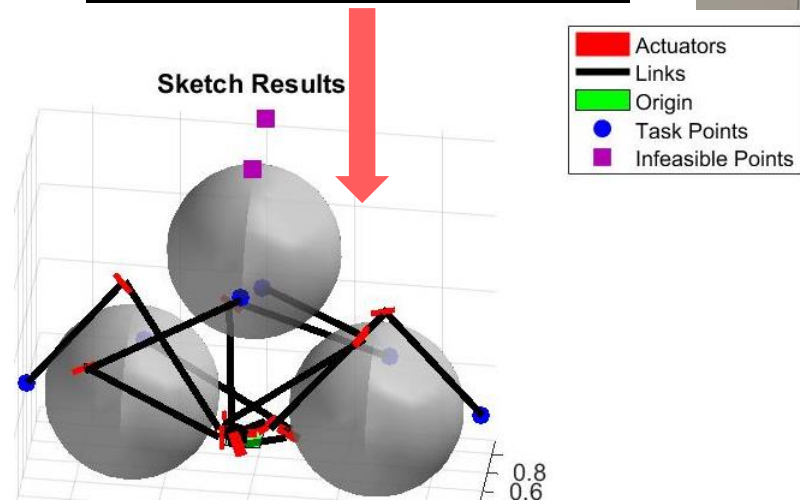
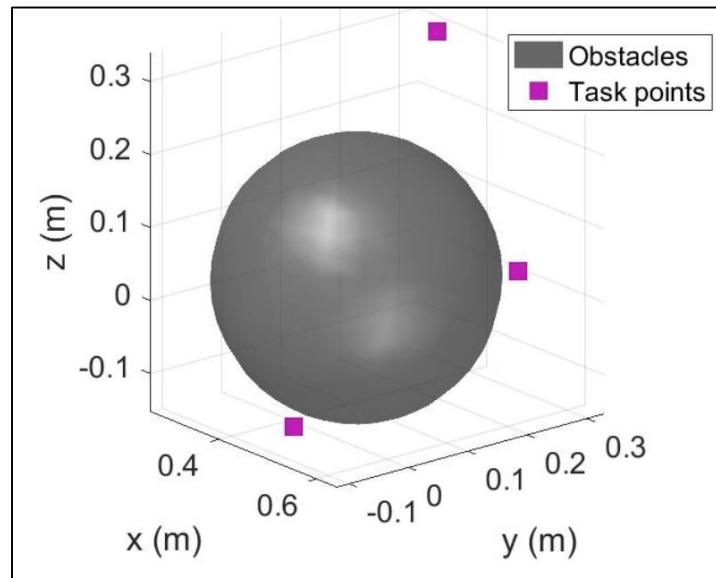
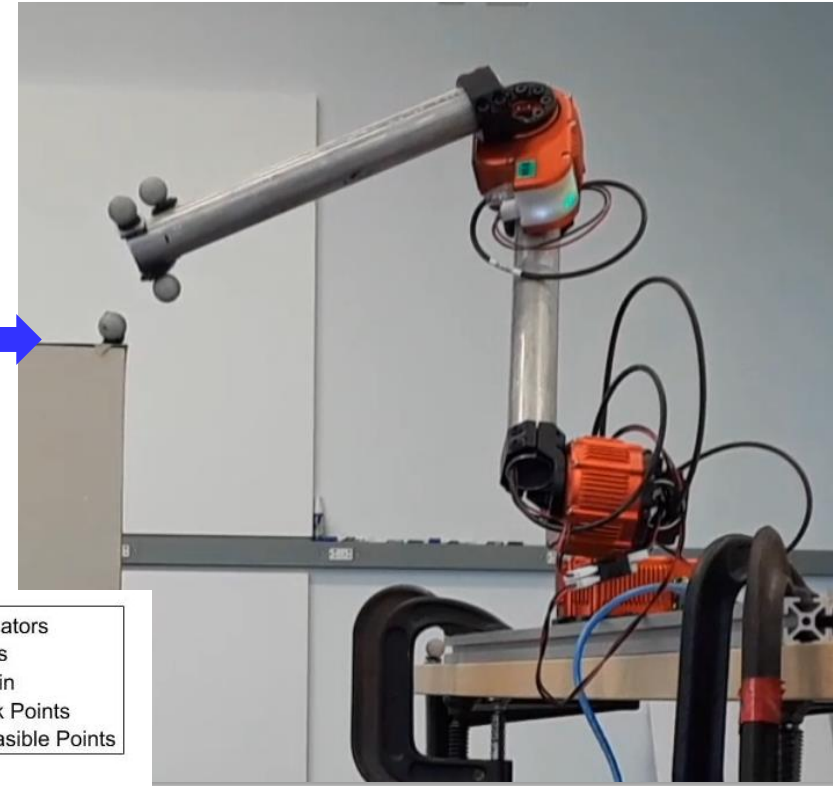
Program  
Synthesis  
(Sketch)



Feedback

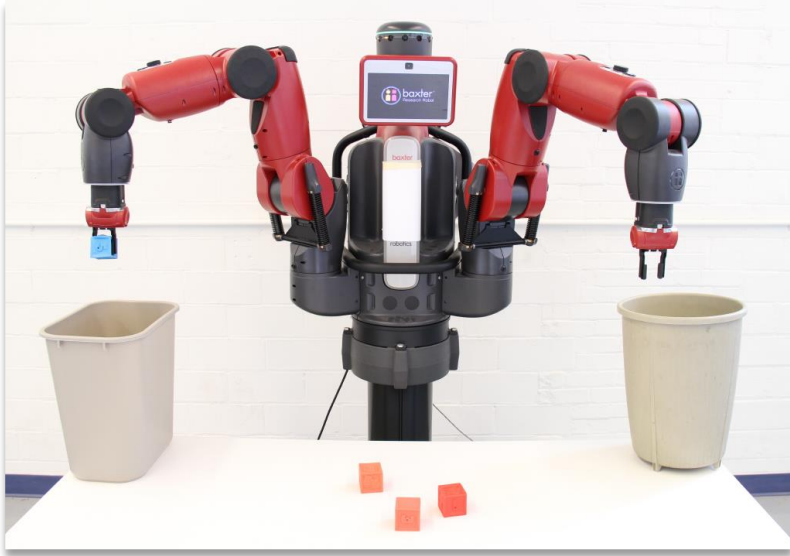


Program  
Synthesis  
(Sketch)



[Campos, Inala, Solar-Lezama, and KG, ICRA '19]





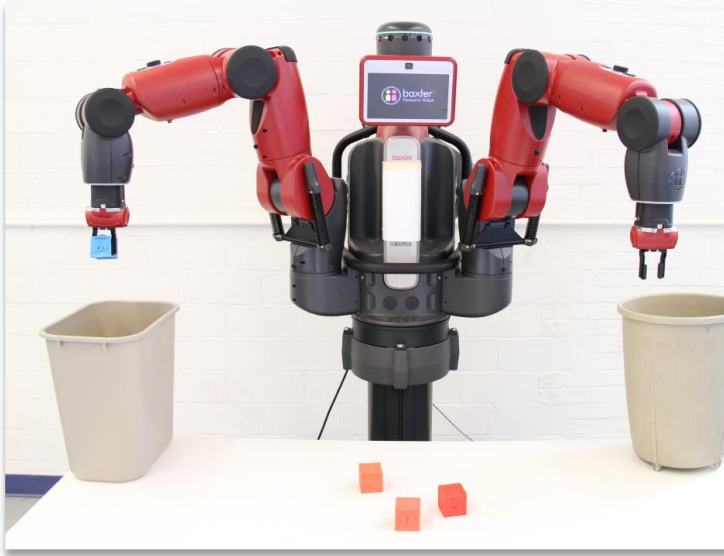
“Pick up the blue block and drop it in the box on your right. Pick up the red block and drop it in the box on your left”

Reactive  
Synthesis  
(LTL)

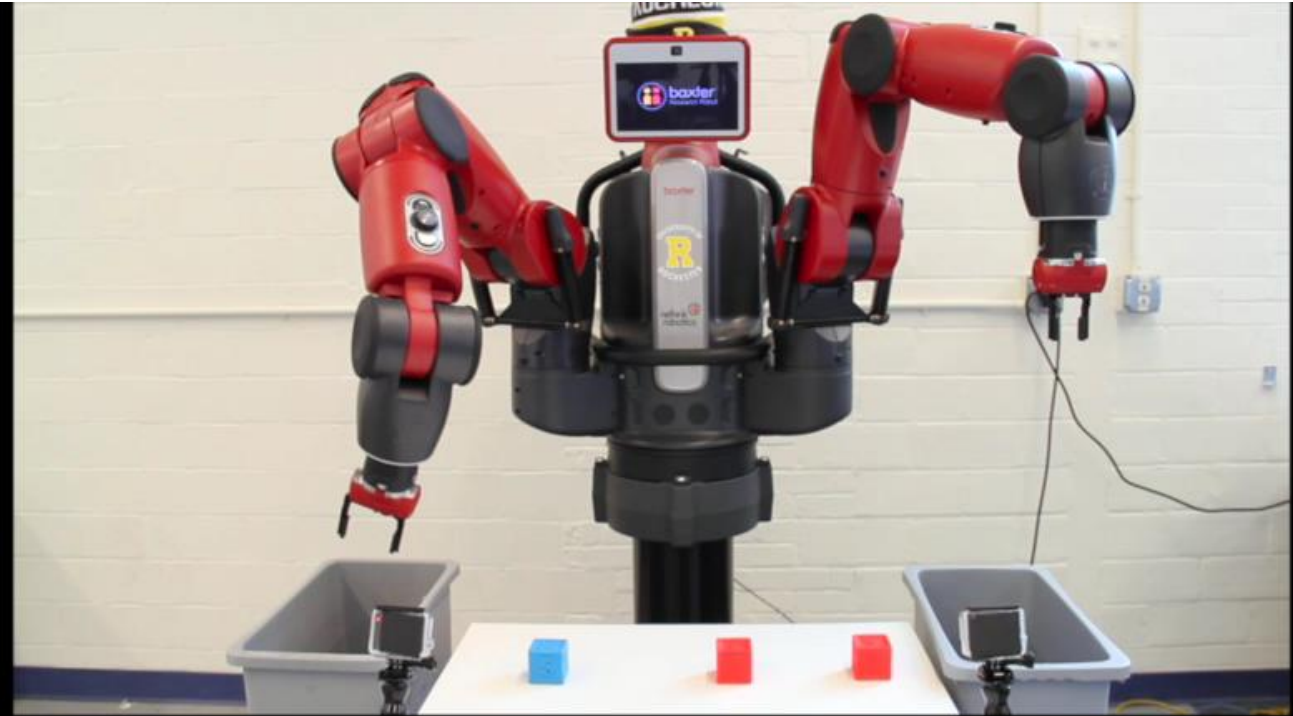
Design

Feedback

[Boteanu, Howard, Arkin, and KG, IROS '16, AAAI Fall Symposium '17]



“Pick up the blue block and drop it in the box on your right. Pick up the red block and drop it in the box on your left”

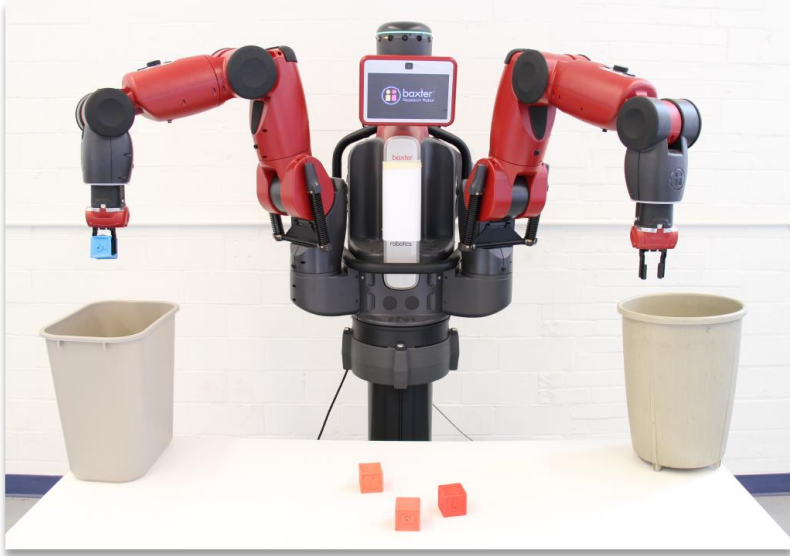


Object ID: cube1; Sensor: blue; Action: pickup\_right



Feedback

[Boteanu, Howard, Arkin, and KG, IROS '16, AAAI Fall Symposium '17]



“Pick up the blue block and drop it in the box on your right. Pick up the red block and drop it in the box on your left”

Reactive  
Synthesis  
(LTL)

Design

**I do not see a red  
block, so I cannot pick  
it up**

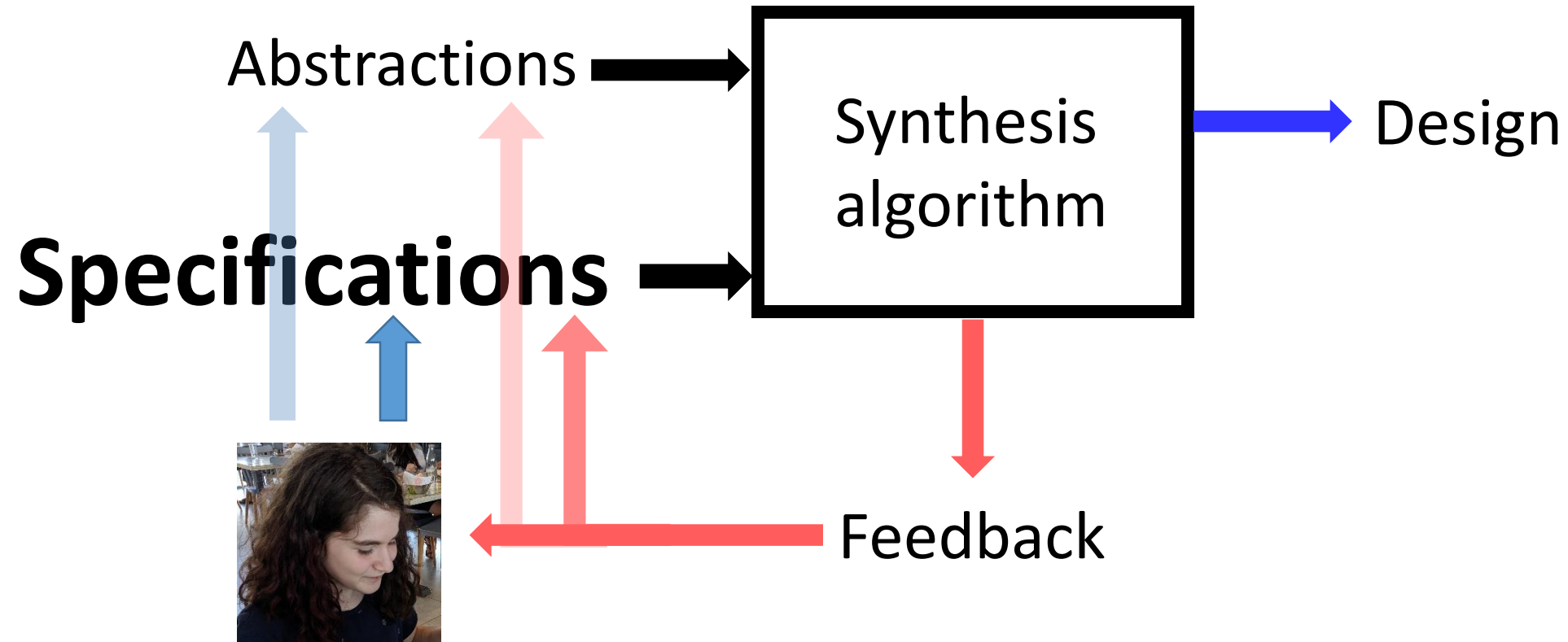
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# Synthesis for Robots: Guarantees and Feedback for Robot Behavior

Hadas Kress-Gazit,<sup>1</sup> Morteza Lahijanian,<sup>2</sup> and Vasumathi Raman<sup>3</sup>

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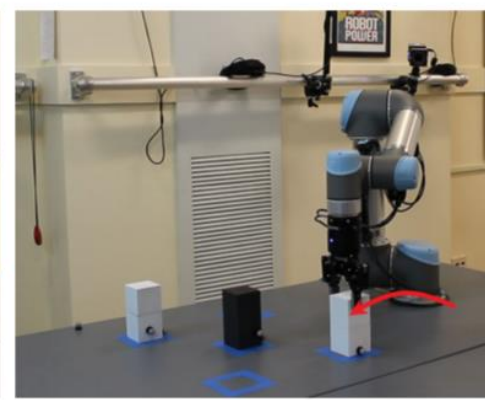
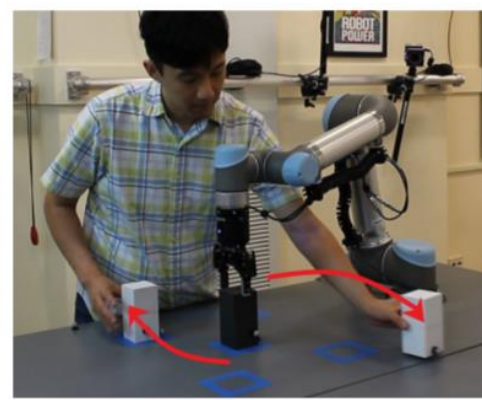
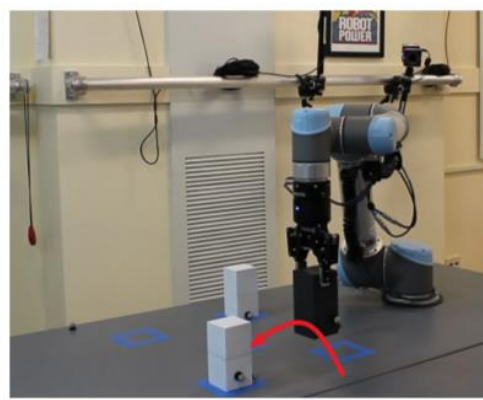
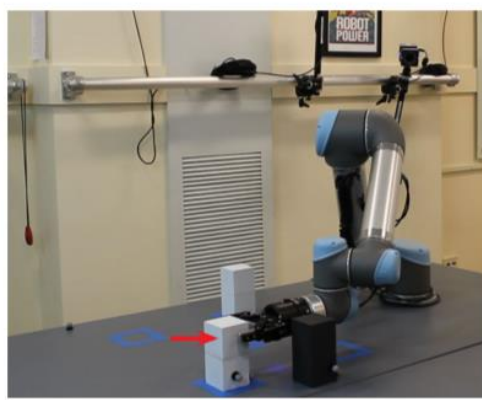
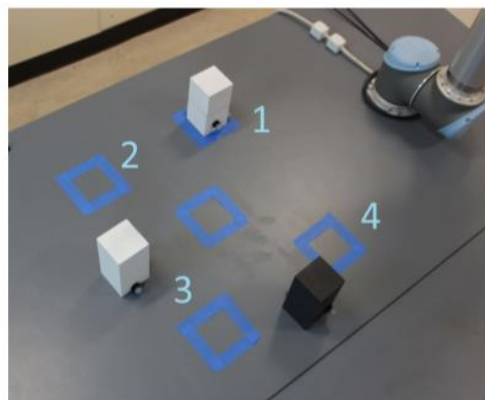
# Specifications

- Formal syntax and semantics
- Capture properties of interest
  - Ordering of events
  - Time
  - Probabilities of success
  - Safety
  - Liveness/goals
- Can be **automatically** and **correctly** transformed into control of a system

# Automated Abstraction of Manipulation Domains for Cost-Based Reactive Synthesis

Keliang He<sup>1</sup>, Morteza Lahijanian<sup>2</sup>, Lydia E. Kavraki<sup>1</sup>, and Moshe Y. Vardi<sup>1</sup>

$$\Diamond \left( p_{\text{black,center}} \wedge \left( (p_{\text{white},1} \wedge p_{\text{white},3}) \vee (p_{\text{white},2} \wedge p_{\text{white},4}) \right) \right)$$



A few more examples of robotics domains, the specification formalism and what is can capture



# Correct-by-construction synthesis for smart manufacturing

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